

# Cloth Compression Using Local Cylindrical Coordinates

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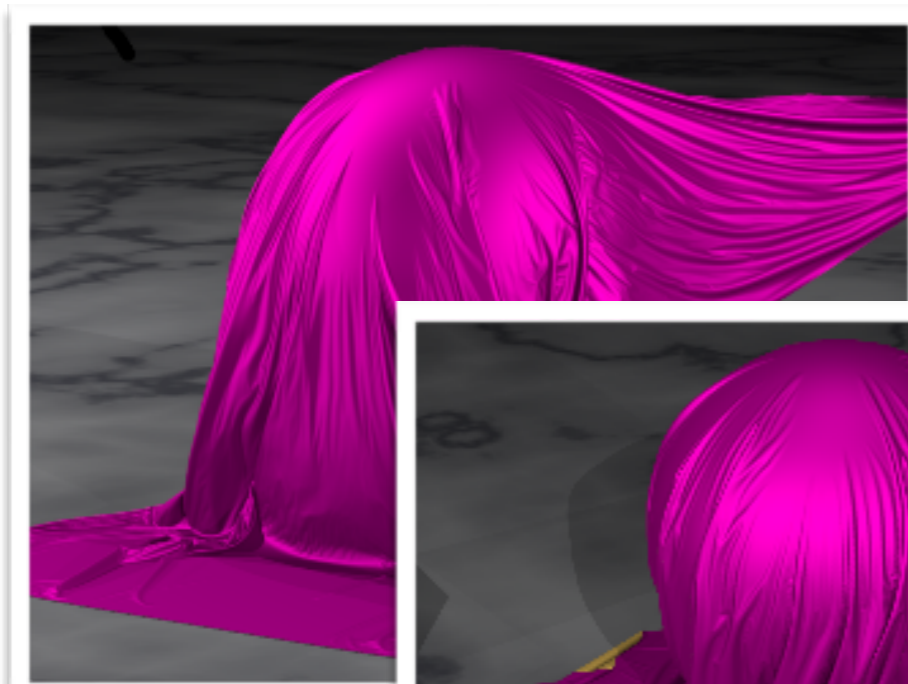
<sup>3</sup>The Chinese University of Hong Kong

# Motivation

- Realistic cloth simulation is **tedious** and **time-consuming**

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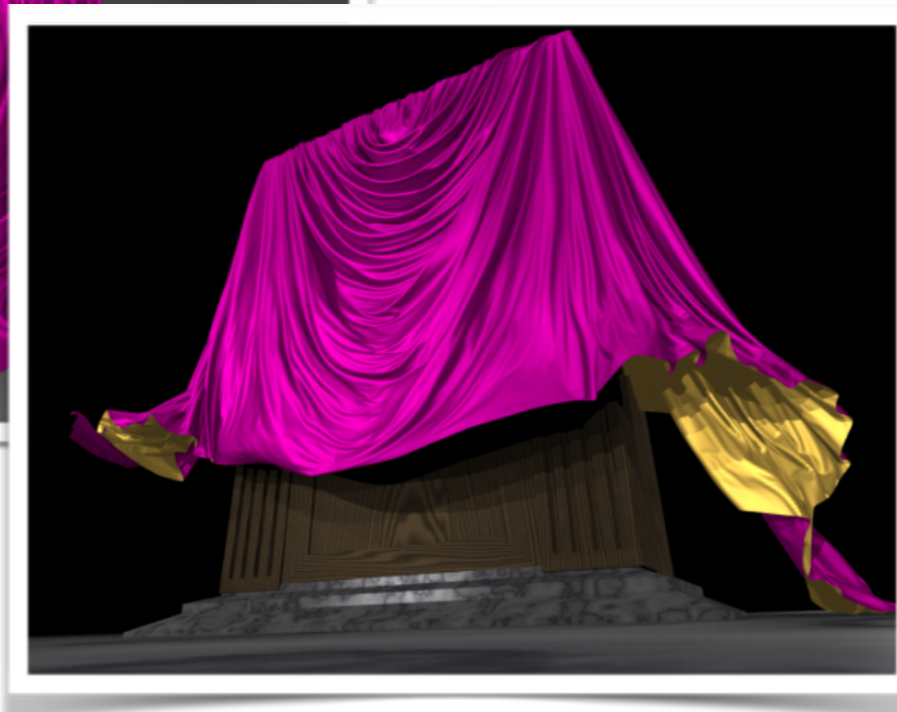
- Realistic cloth simulation is **tedious** and **time-consuming**



✓ **Large DoFs**

✓ **Nonlinear & stiff system**

✓ **Complex collisions**



*[Selle et al.09]*

# Motivation

- Trends: mobile devices gets largely populated
  - ▶ Small and flexible
  - ▶ Limited computational resources
- Advanced simulation algorithm
  - ▶ Multigrid, multilevel, projective dynamics...
  - ▶ Still costly for mobile terminals

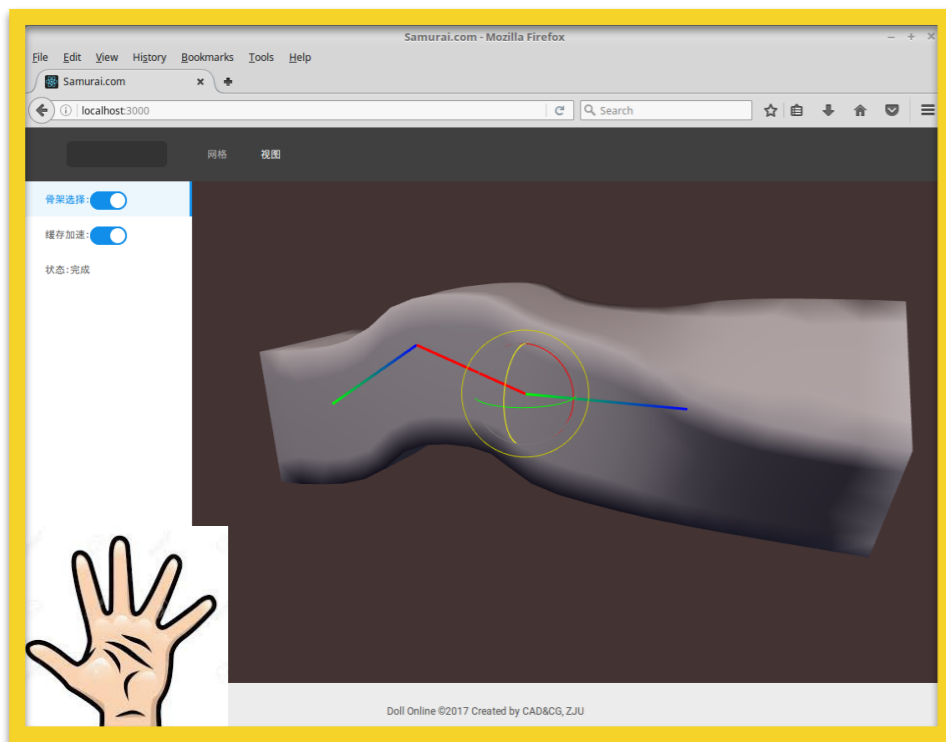


# Motivation

- Possible solution: BS architecture

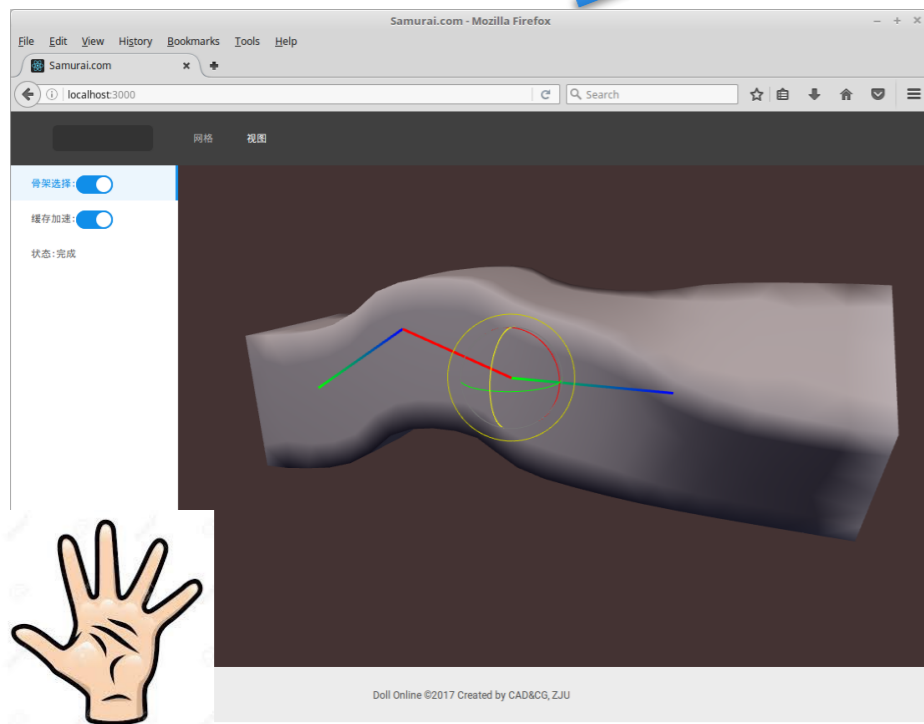
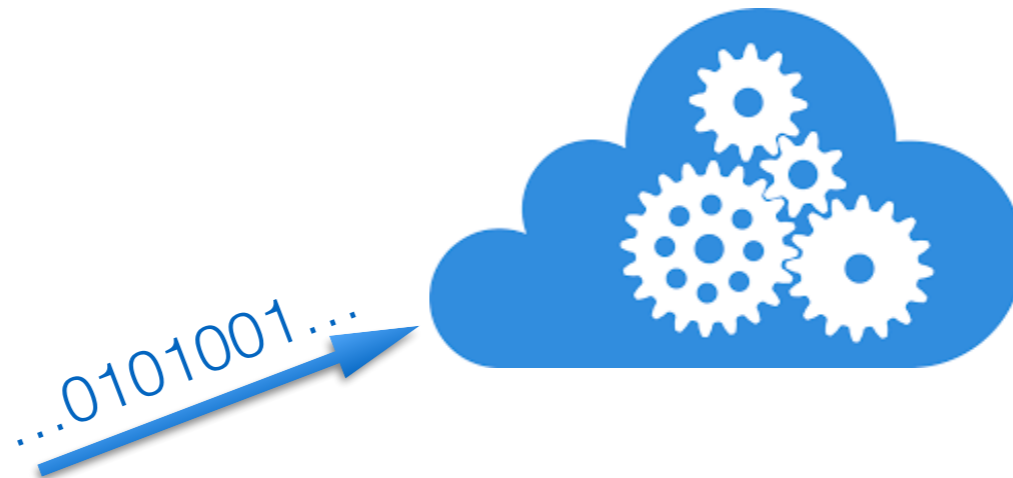
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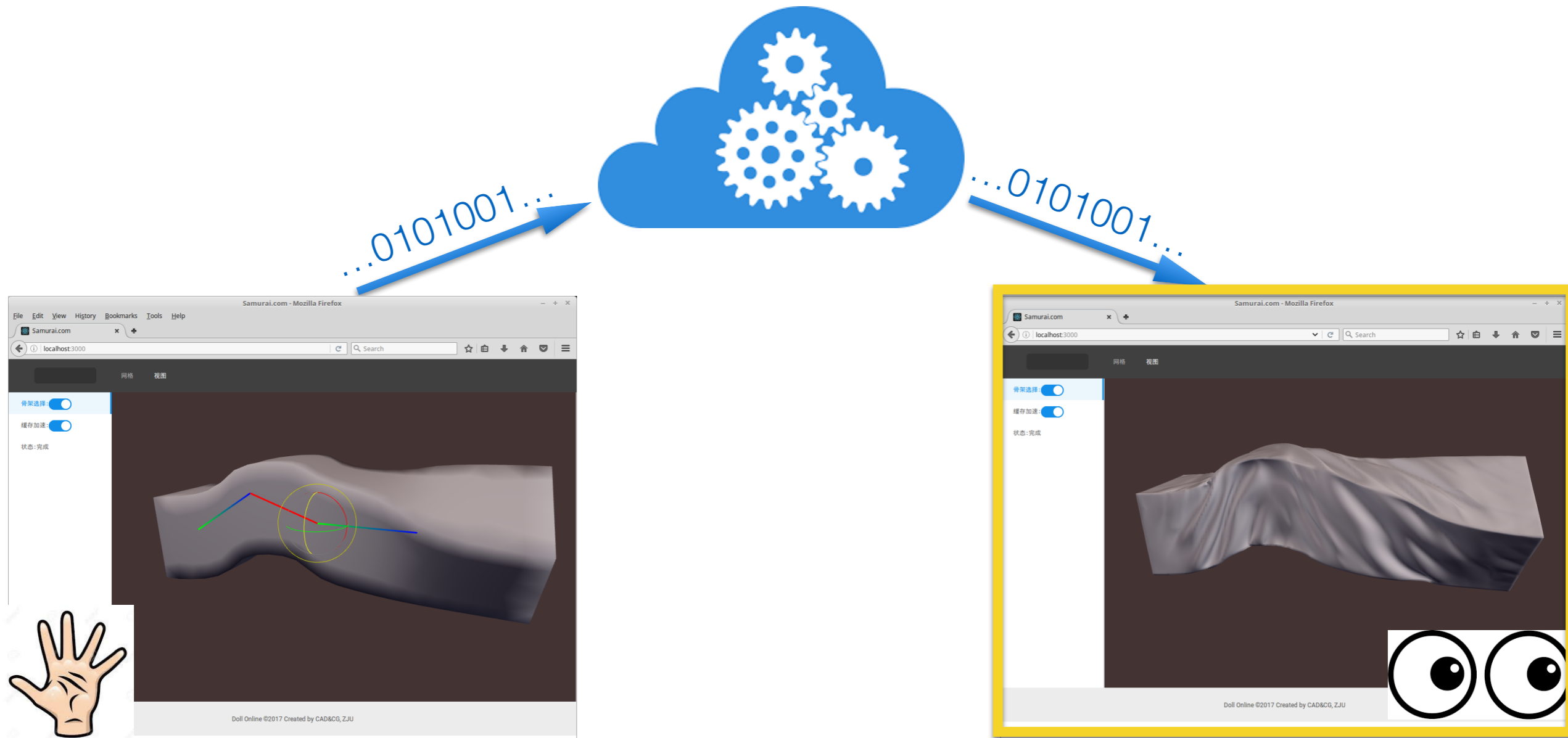
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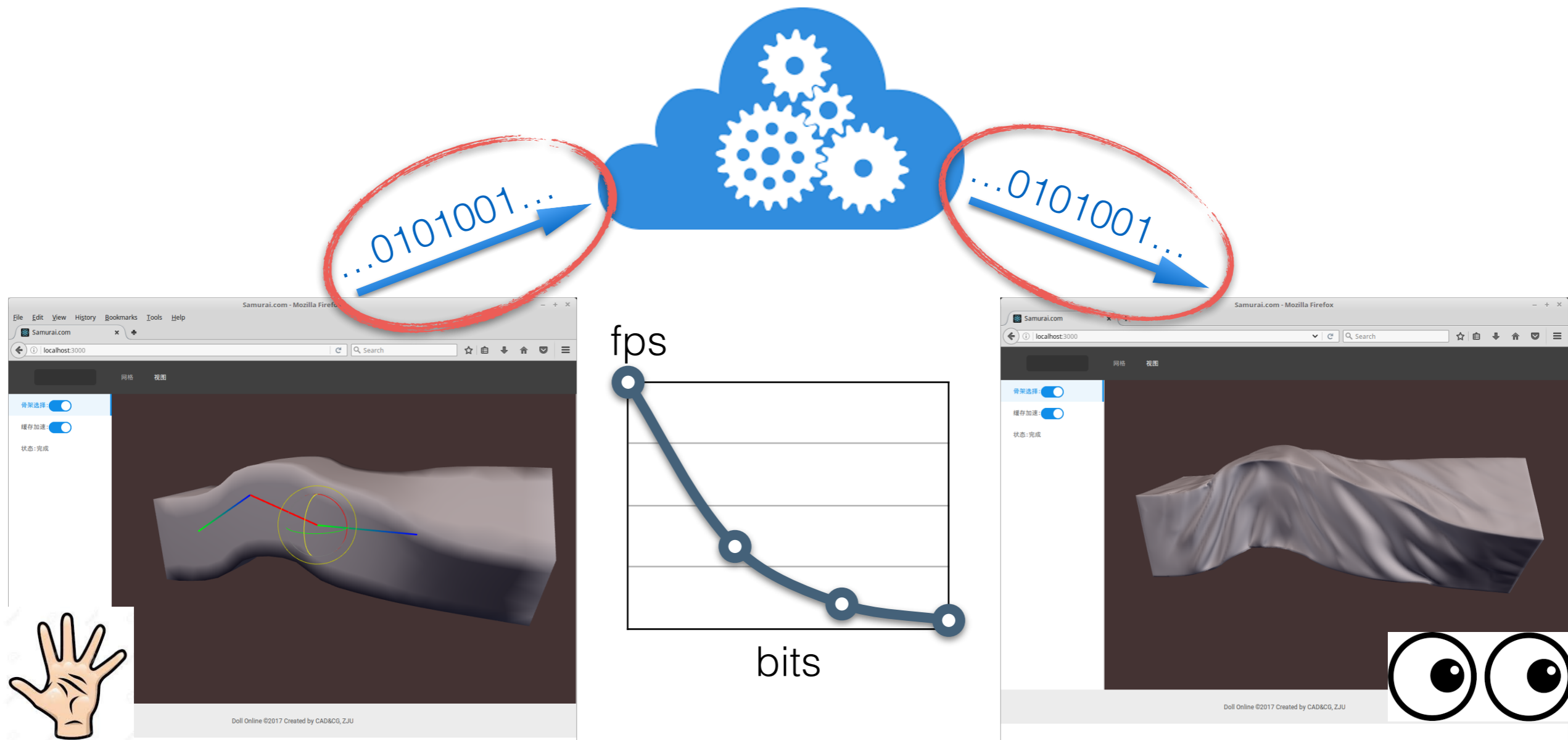
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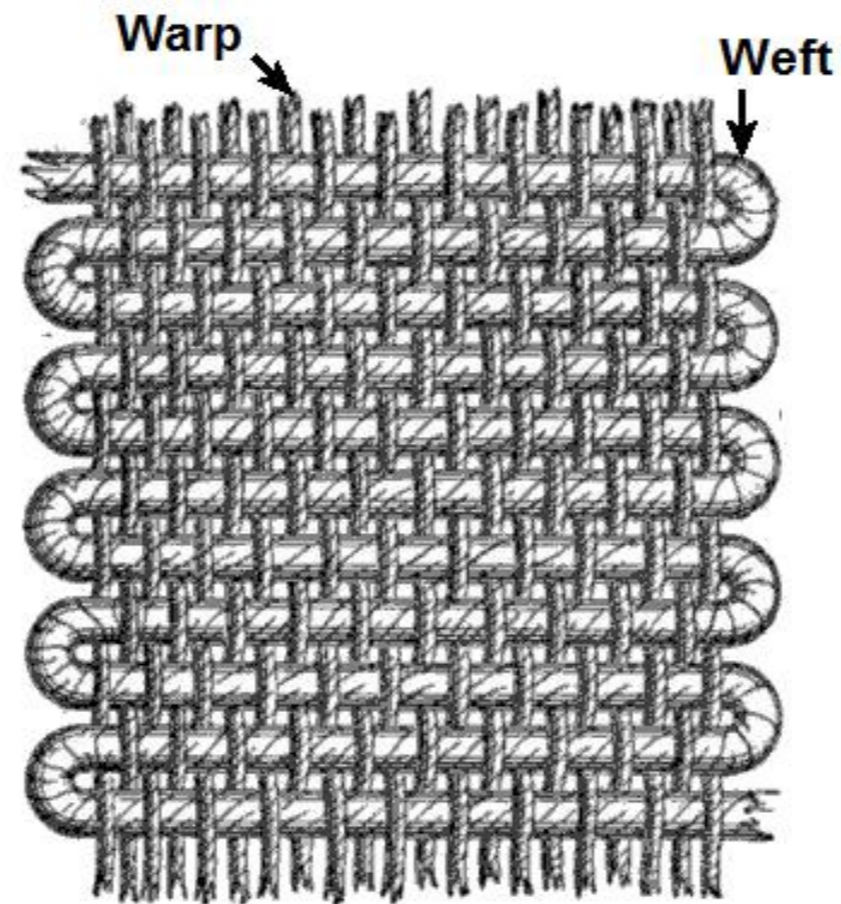
- Possible solution: BS architecture



# Rationale

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- Cloth generally does not noticeably stretch



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- Cloth generally does not noticeably stretch
- Numerically: strain limiting
- Degrading simulation efficiency



[Goldenthal et al. 07]



[Thomaszewski et al. 09]



[Wang et al. 10]

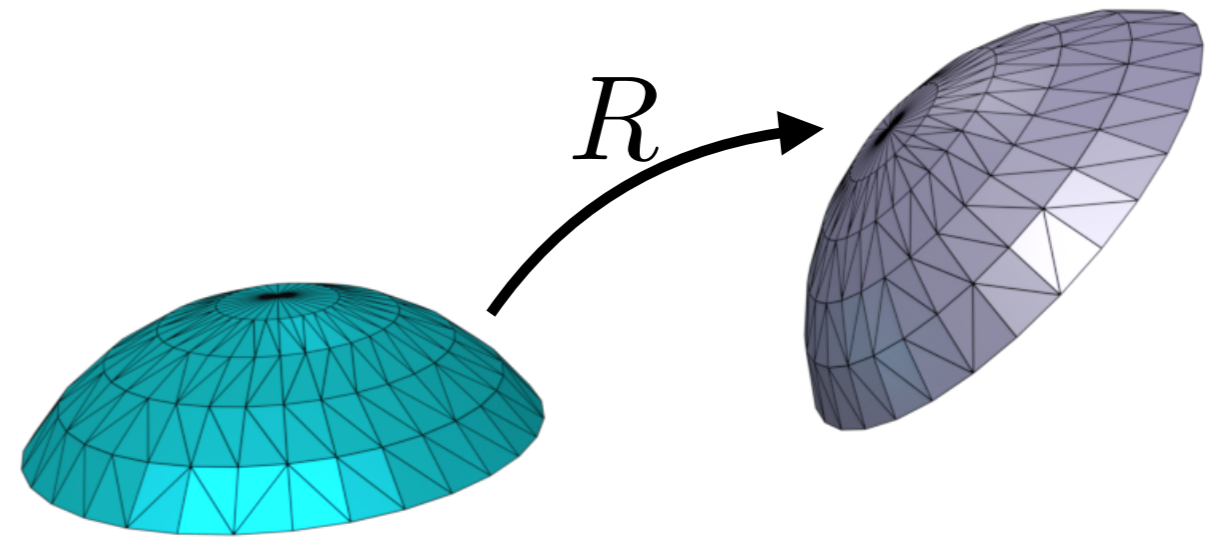
# Rationale

- Numerics becomes more evolved, but geometry are intrinsically *“simpler”*
- More compact representation?

# Previous Work

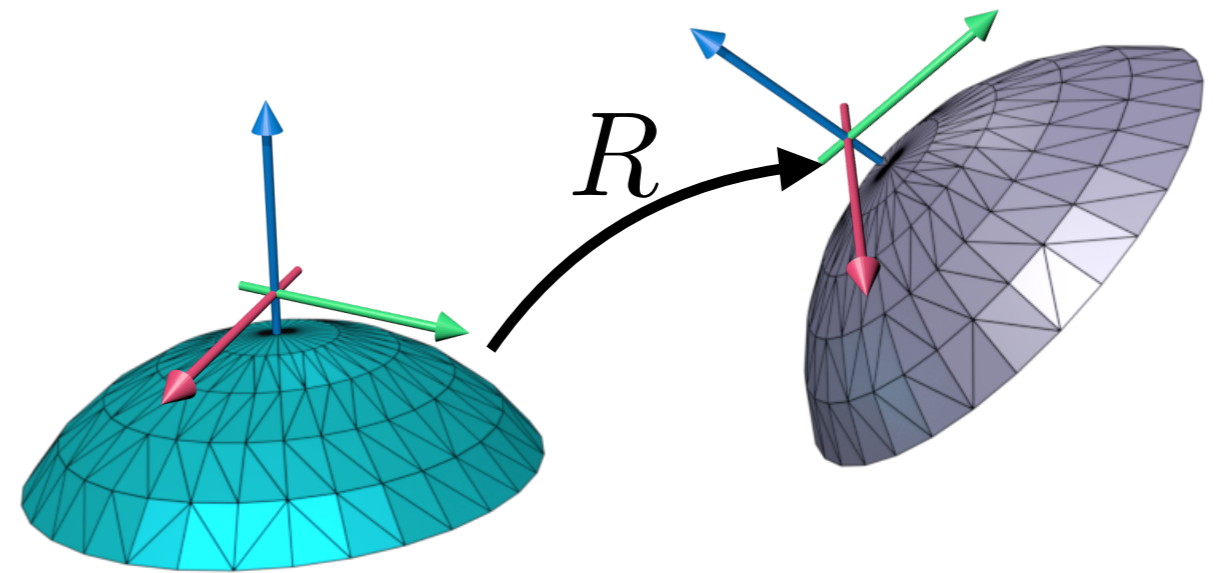
# Previous Work

- Predictive method
  - Local rigid transformation



# Previous Work

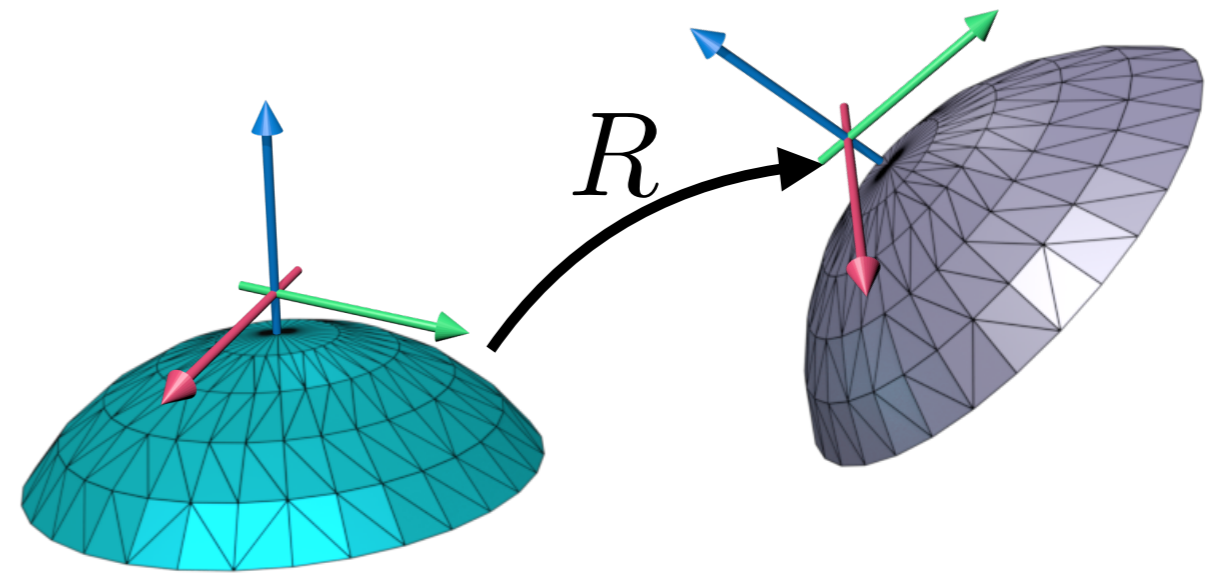
- Predictive method
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# Previous Work



- Predictive method
  - Local rigid transformation



- Spectral methods
  - Geometrically smooth

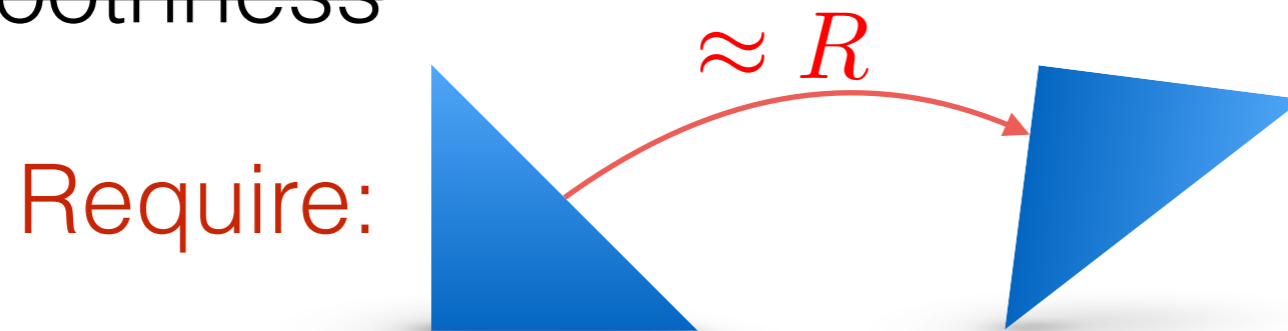


$$\begin{matrix} T \\ N \end{matrix} = \begin{matrix} r \\ N \end{matrix} \times \begin{matrix} T \\ r \end{matrix}$$

 subspace basis  
 subspace coords

# Basic Idea

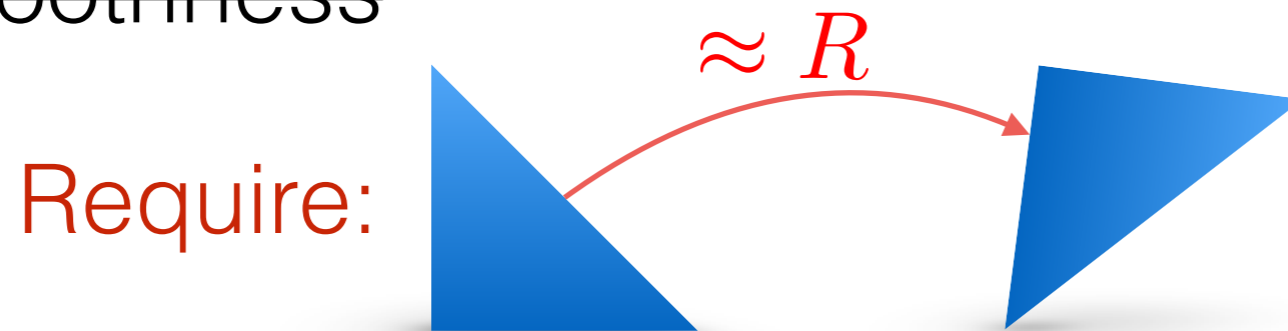
- Assumption: ~~Local rigidity and geometric smoothness~~



- Decompose the deformation into two separate parts
  - ▶ In-plane: small stretch or shear
  - ▶ Out-plane: large bending or torsion

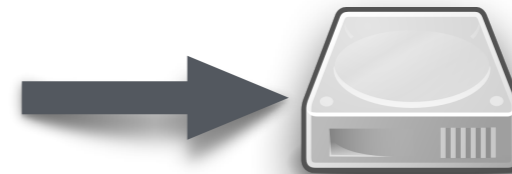
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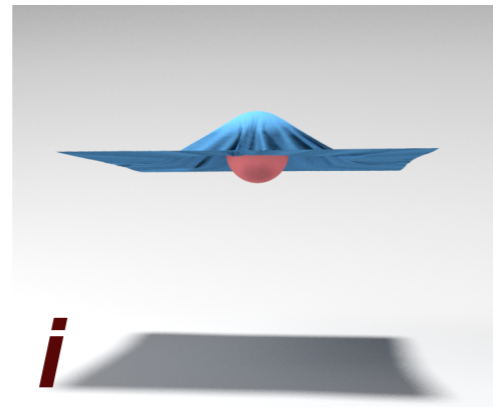
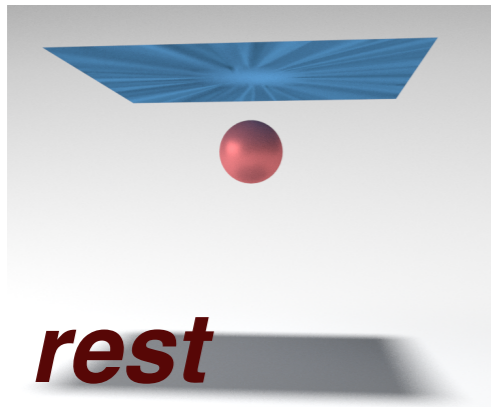
▶ In-plane: small stretch or shear



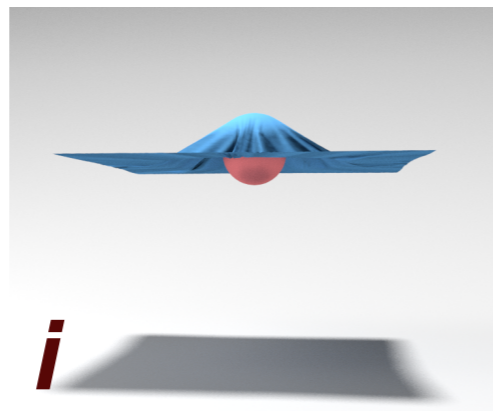
▶ Out-plane: large bending or torsion



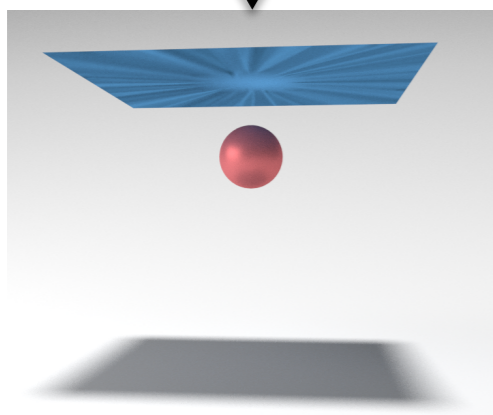
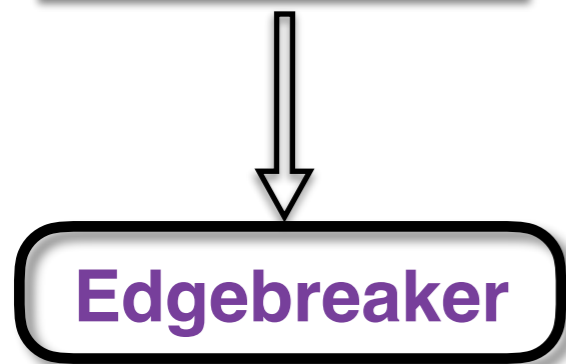
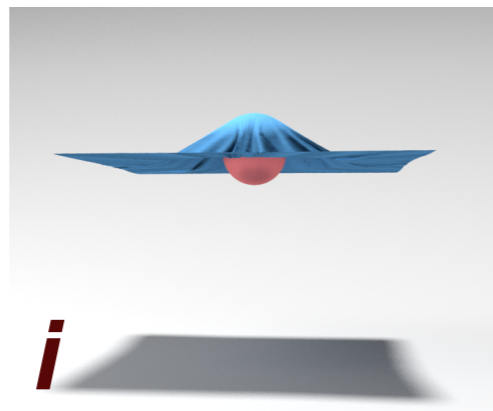
# Overview



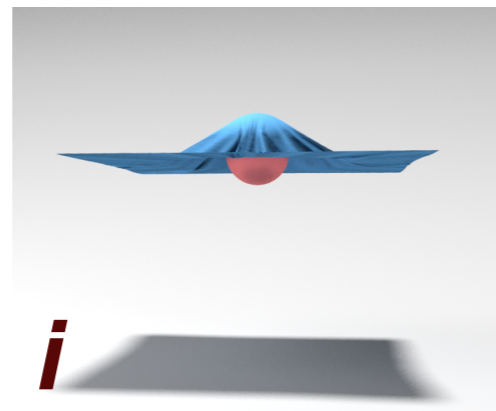
# Overview



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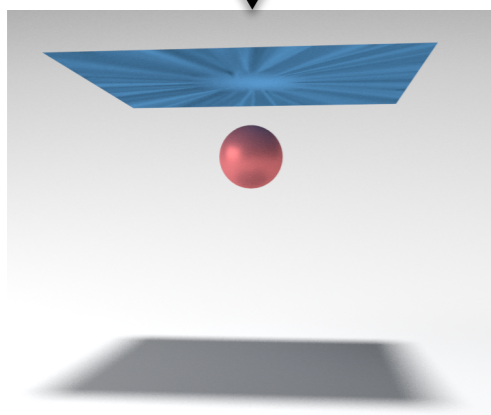


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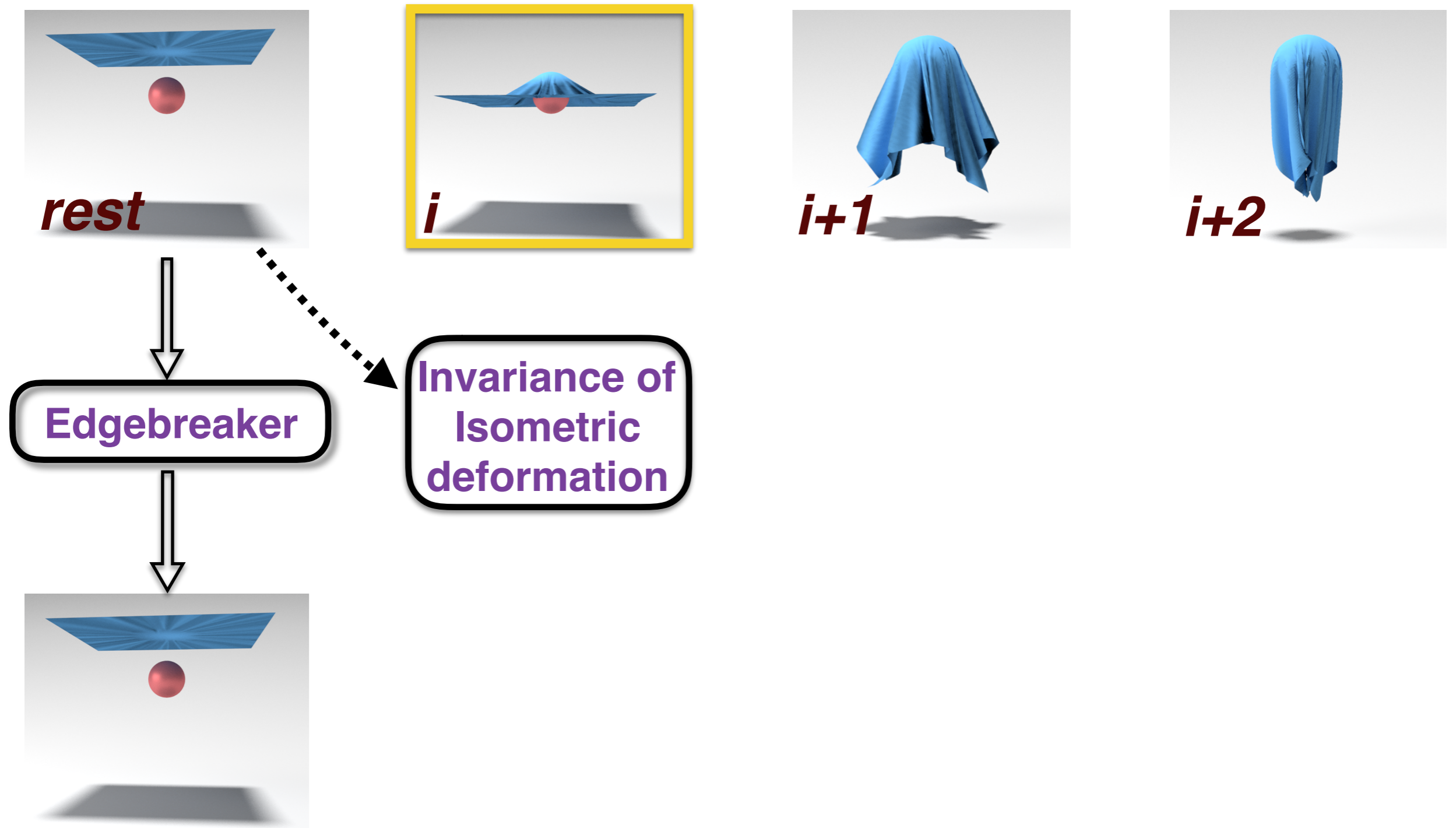


Edgebreaker

Invariance of Isometric deformation

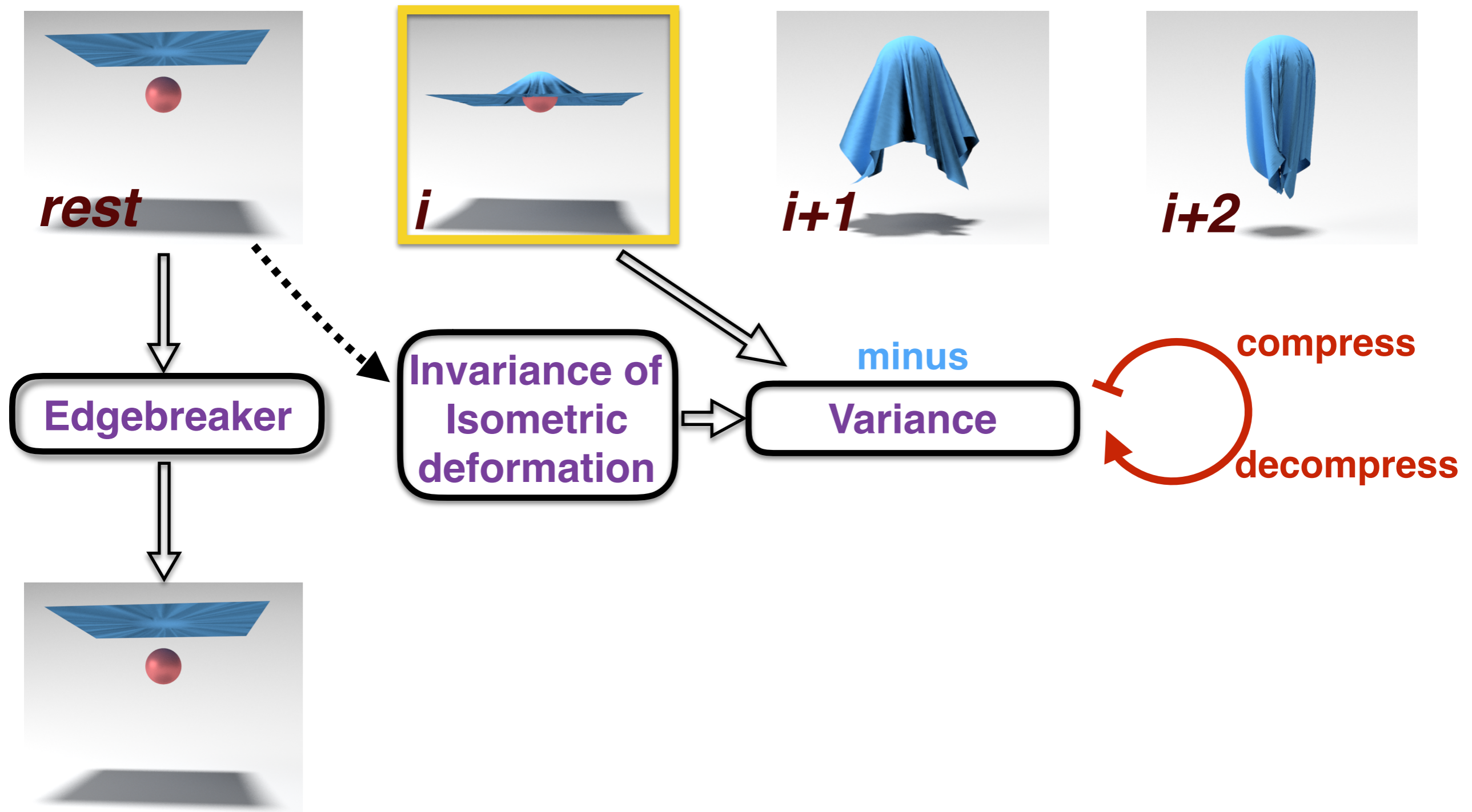


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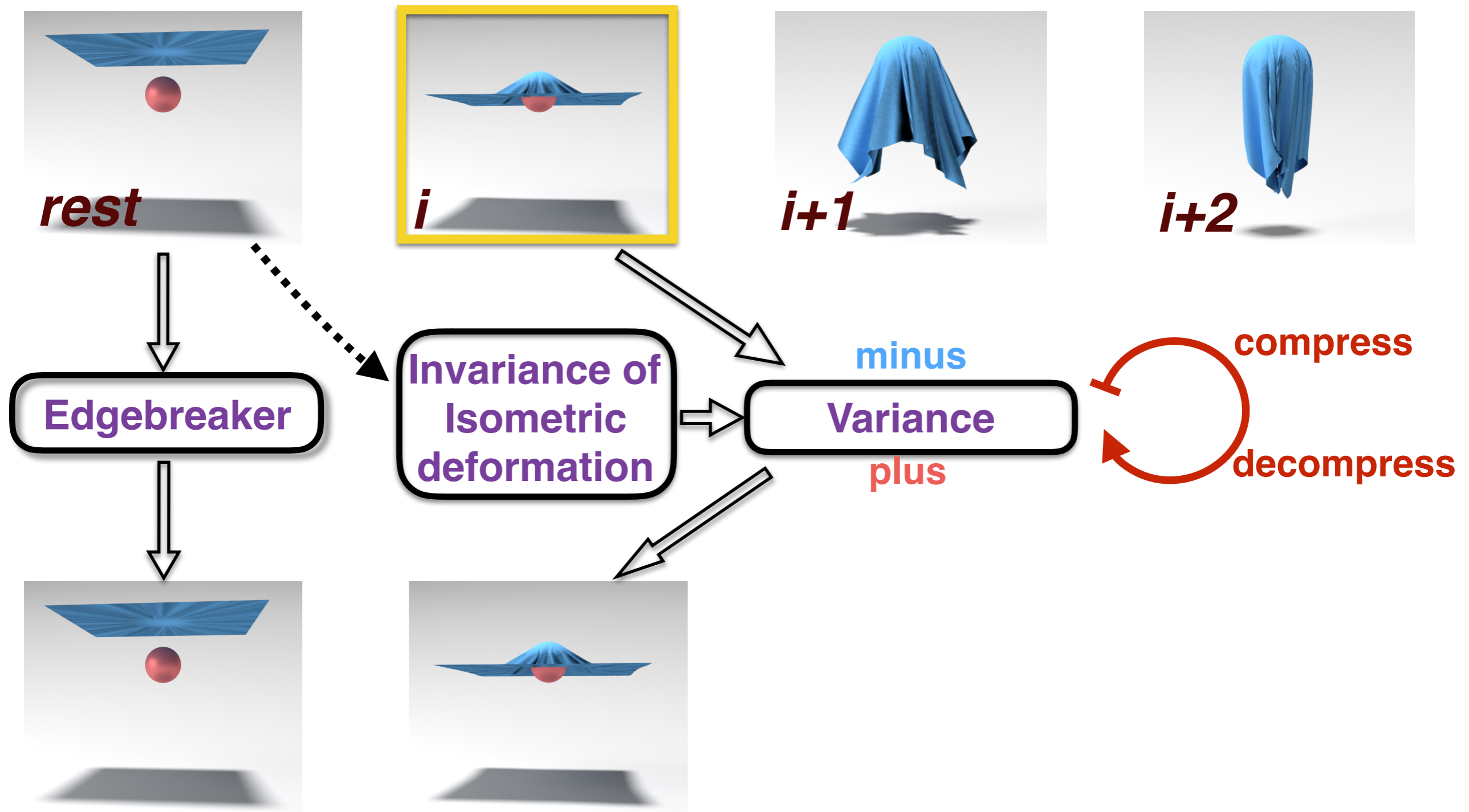




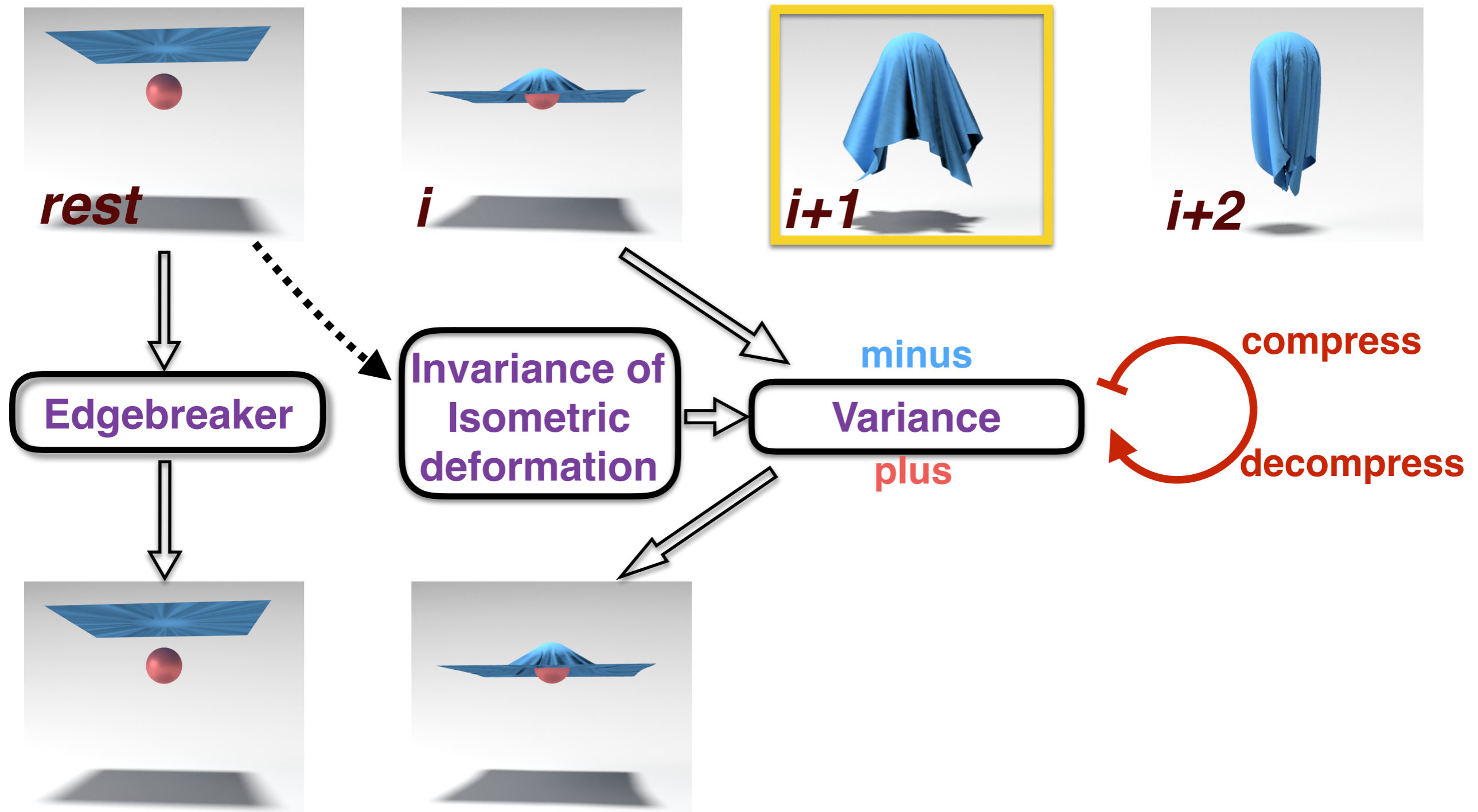
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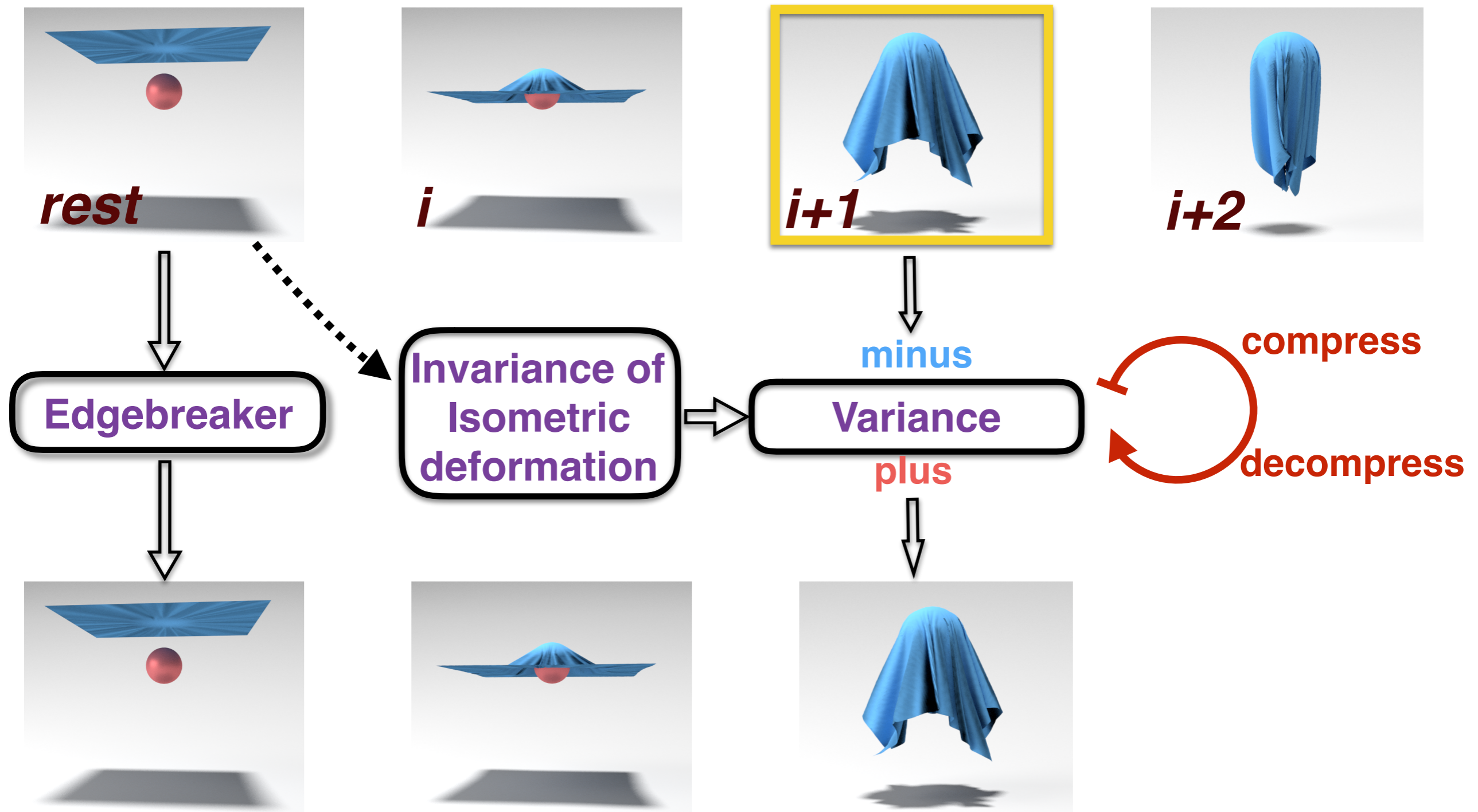
# Overview



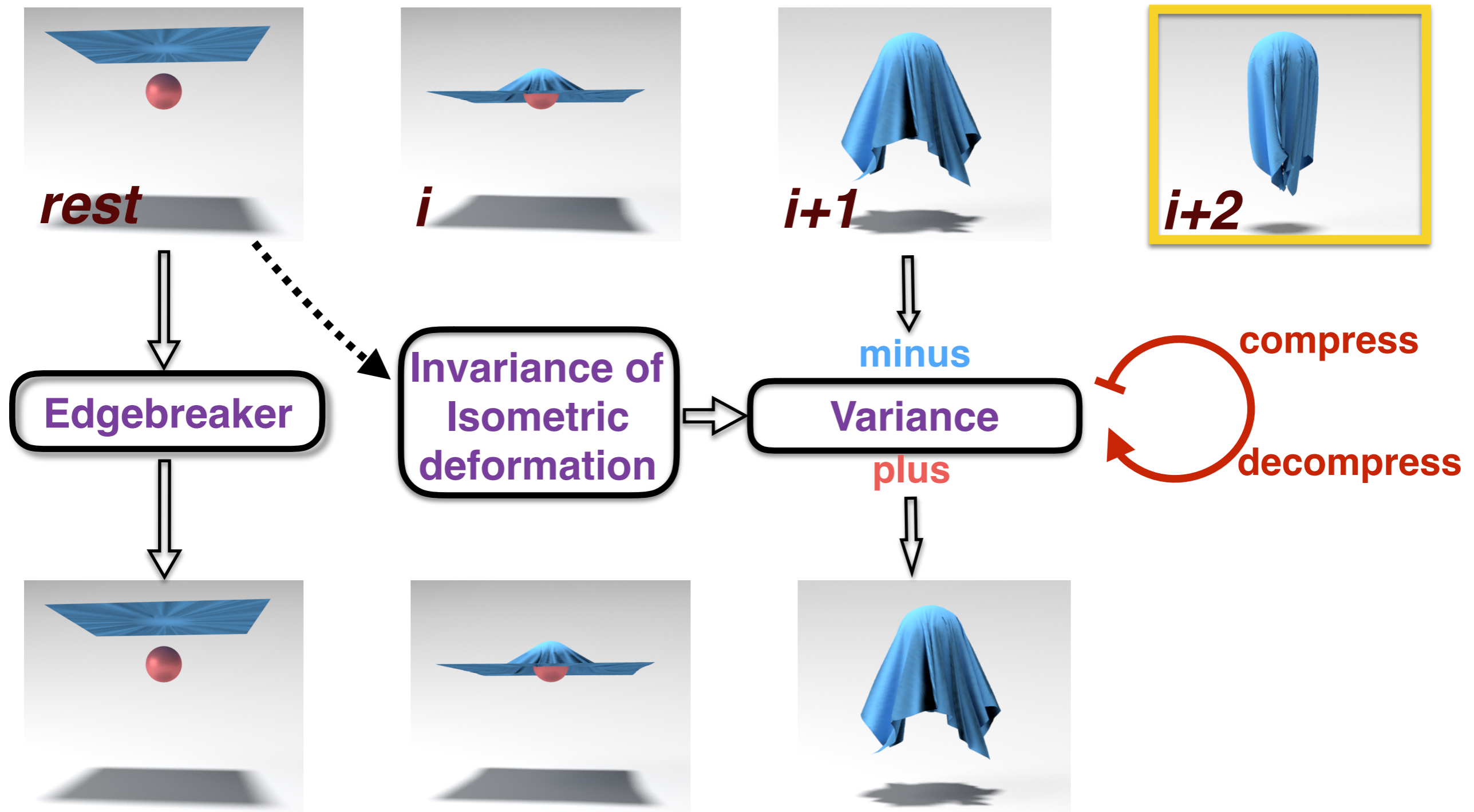
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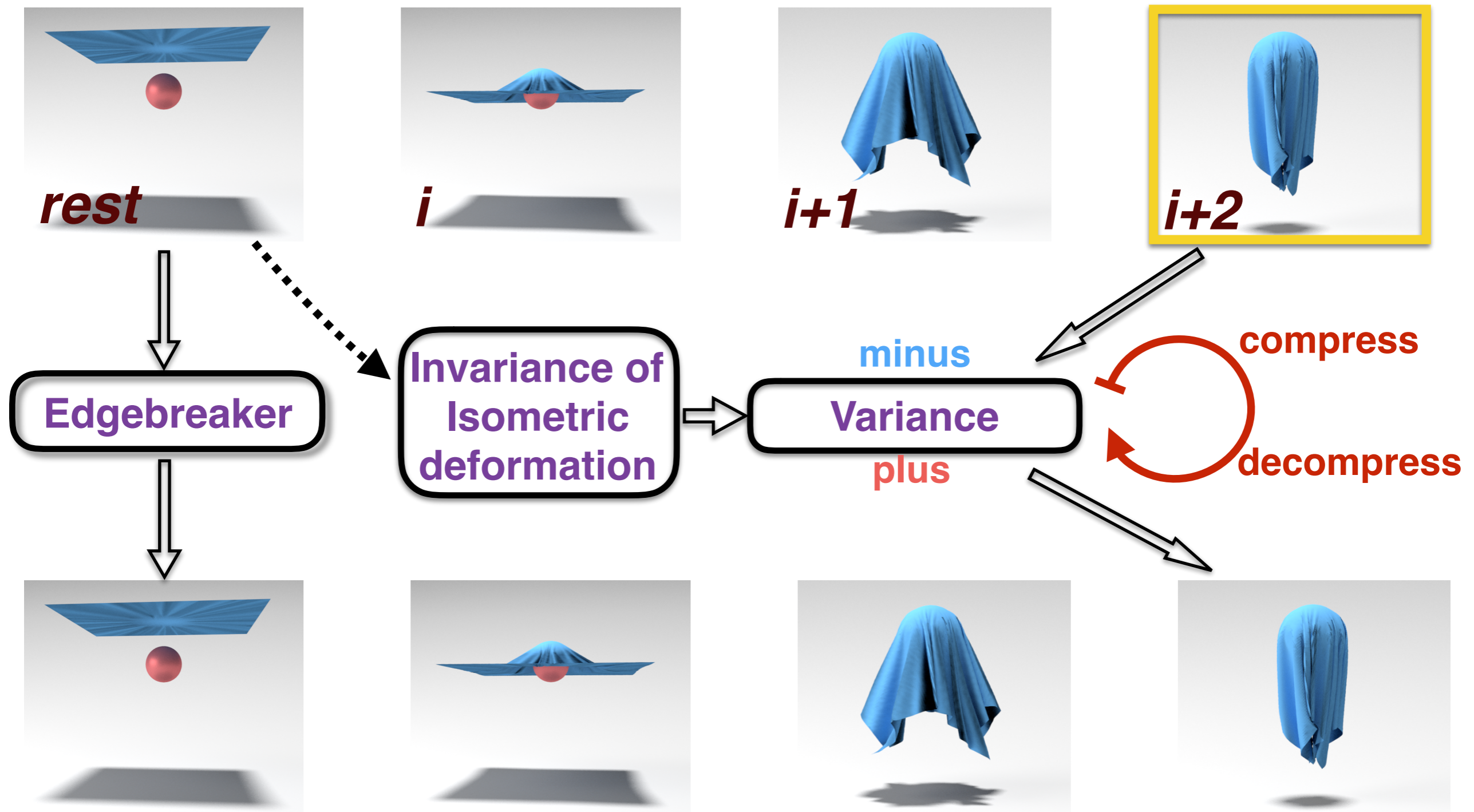
# Overview



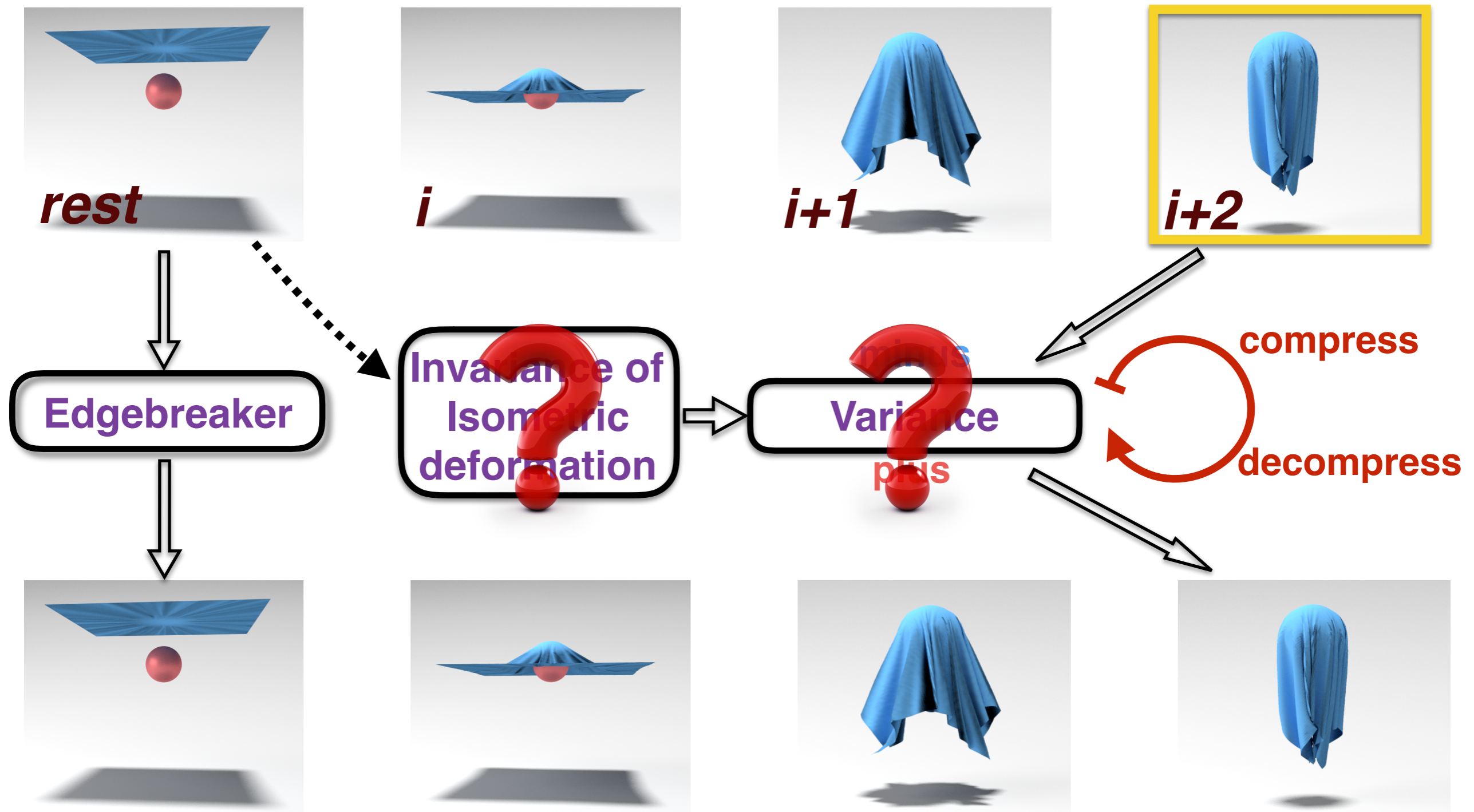
# Overview



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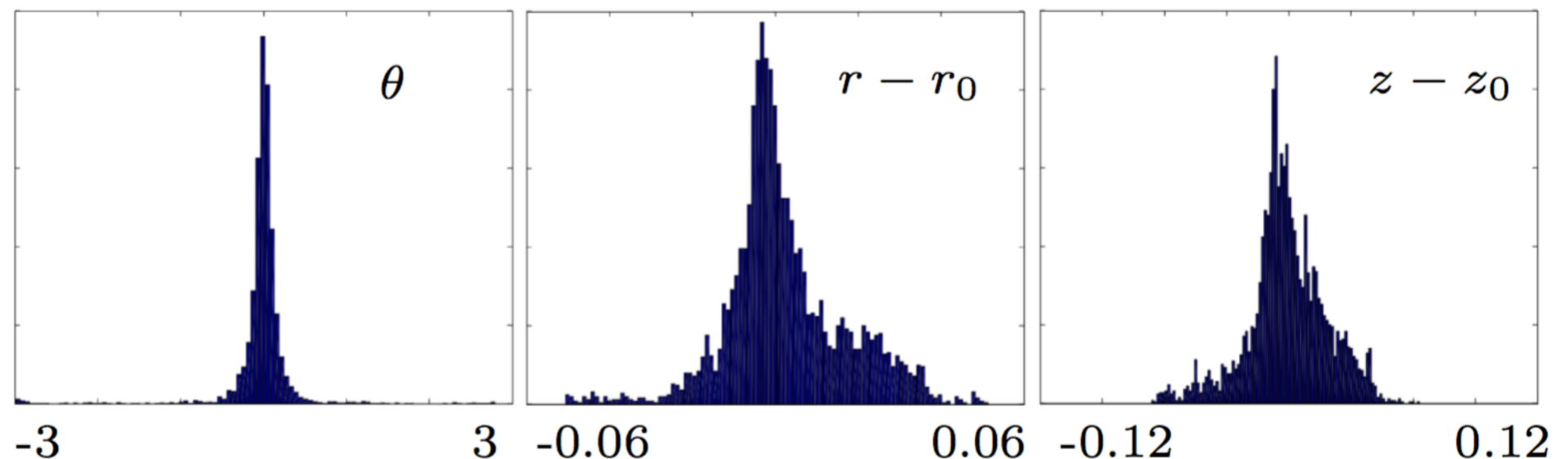
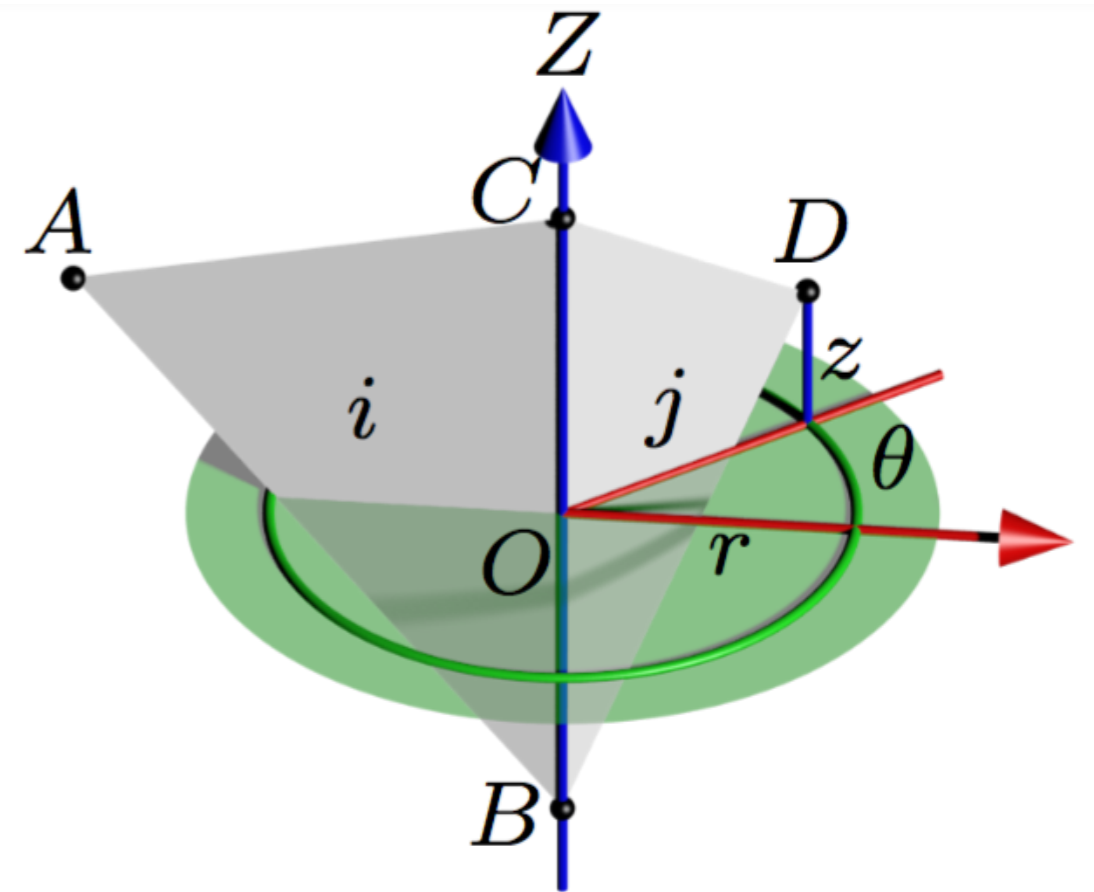


# Overview



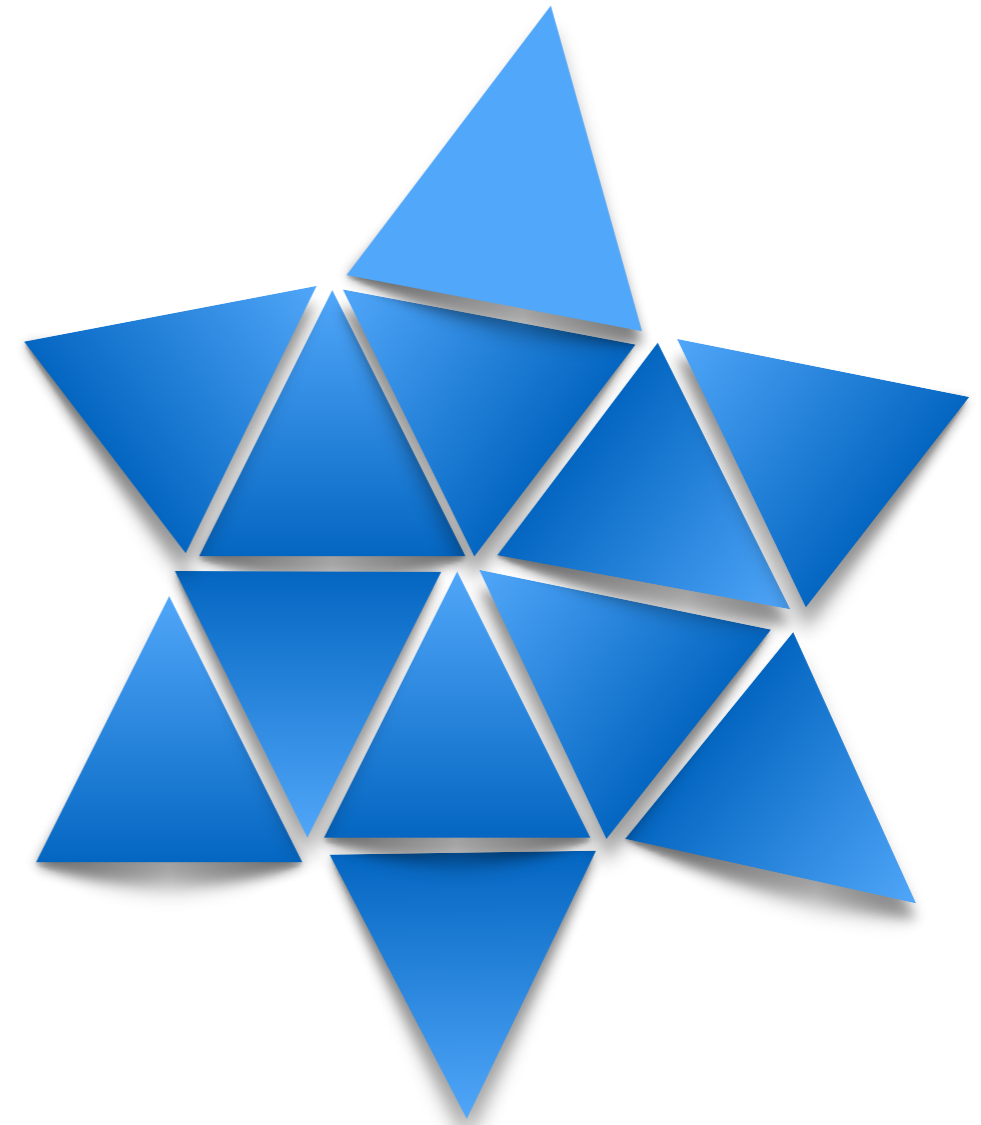
# Local Cylindrical Coordinate (LCC)

- For a triangle pair,  
$$(x_1^D, x_2^D, x_3^D) \rightleftharpoons (\theta, r, z),$$
wrt.  $\Delta ABC$
- Normalization:  $\Delta/L$
- Cloth with strain limiting  
(upper bound for stretch  
ratio 5%)



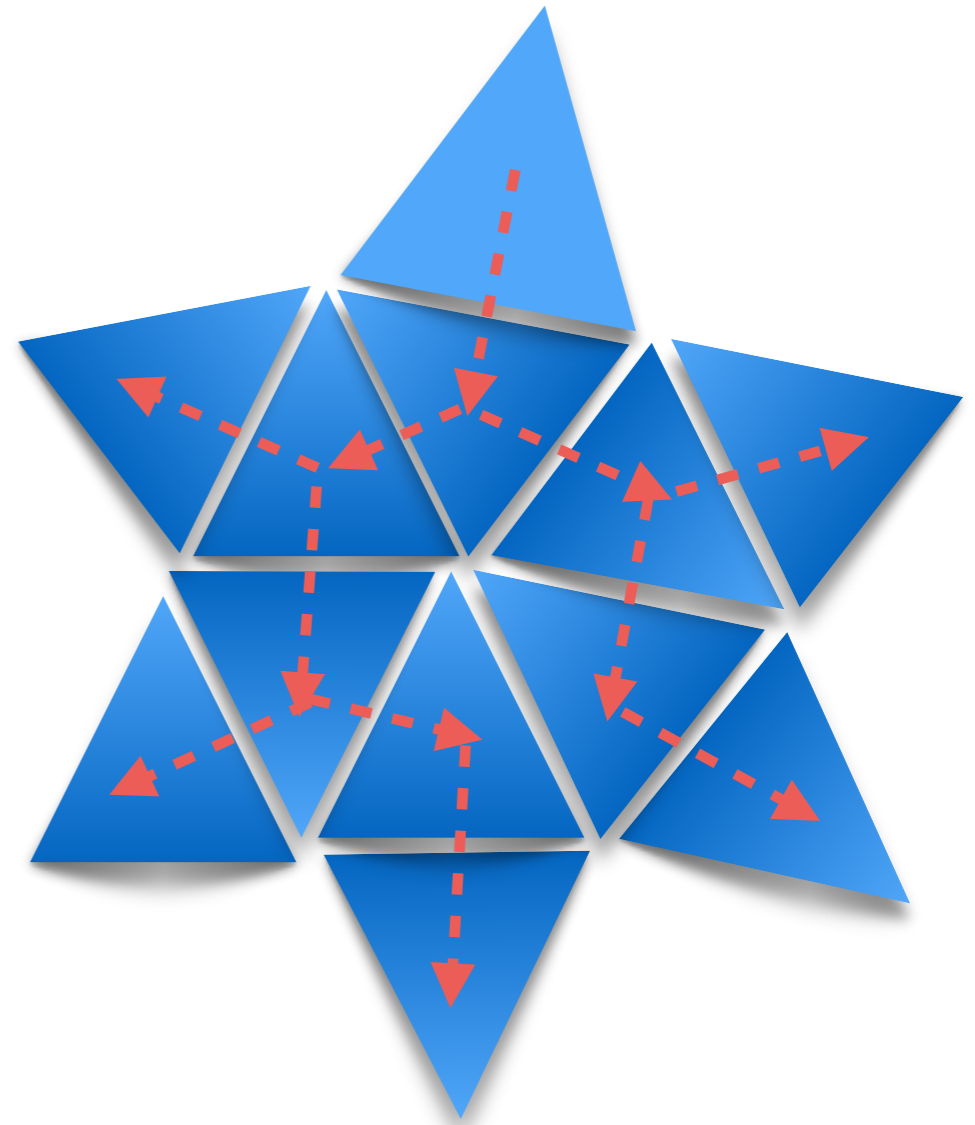


# Encoding & Decoding



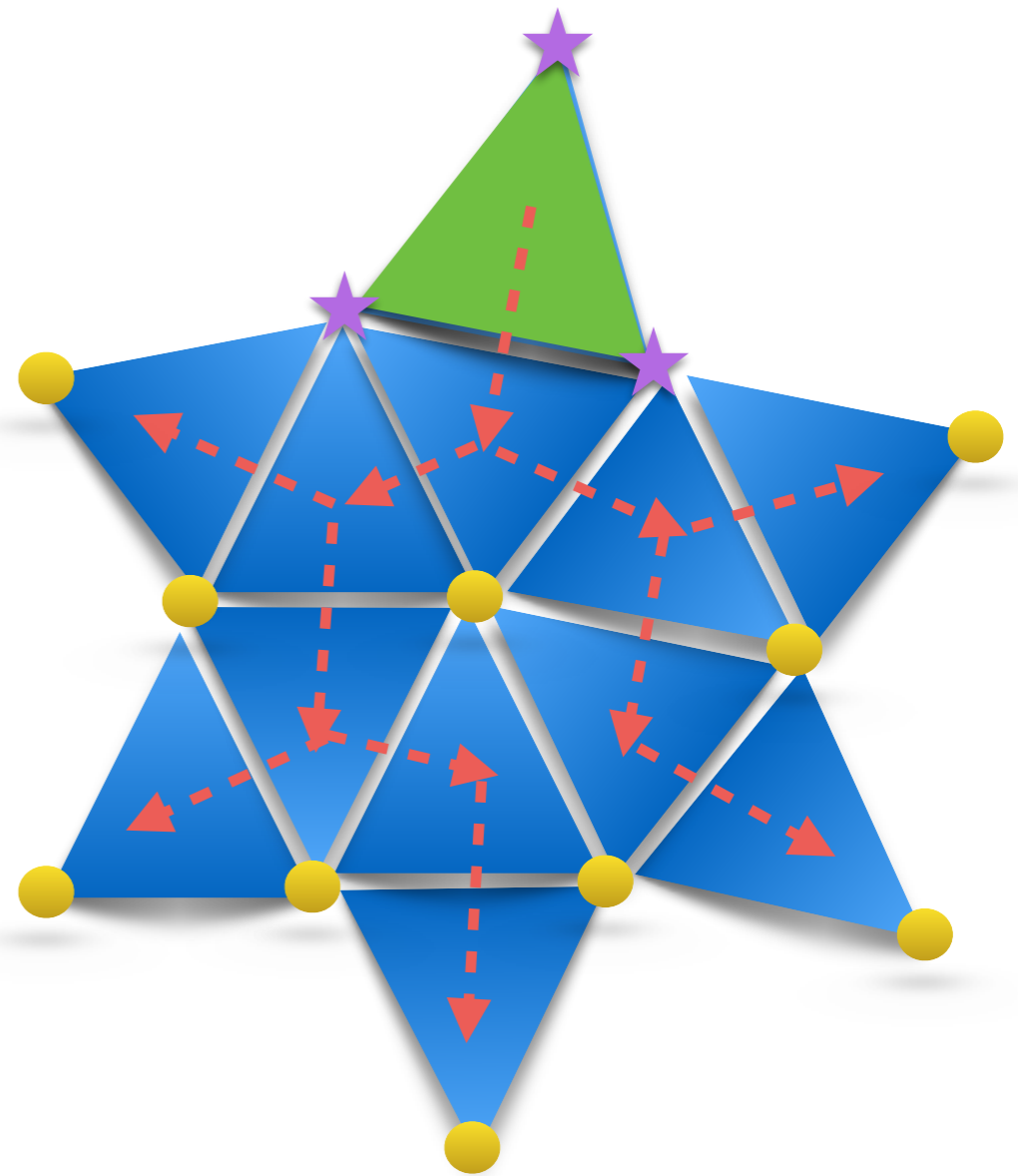
# Encoding & Decoding

- Construct spanning tree



# Encoding & Decoding

- Construct spanning tree
- Select root and traverse the tree



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- Construct spanning tree
- Select root and traverse the tree

- Encoding

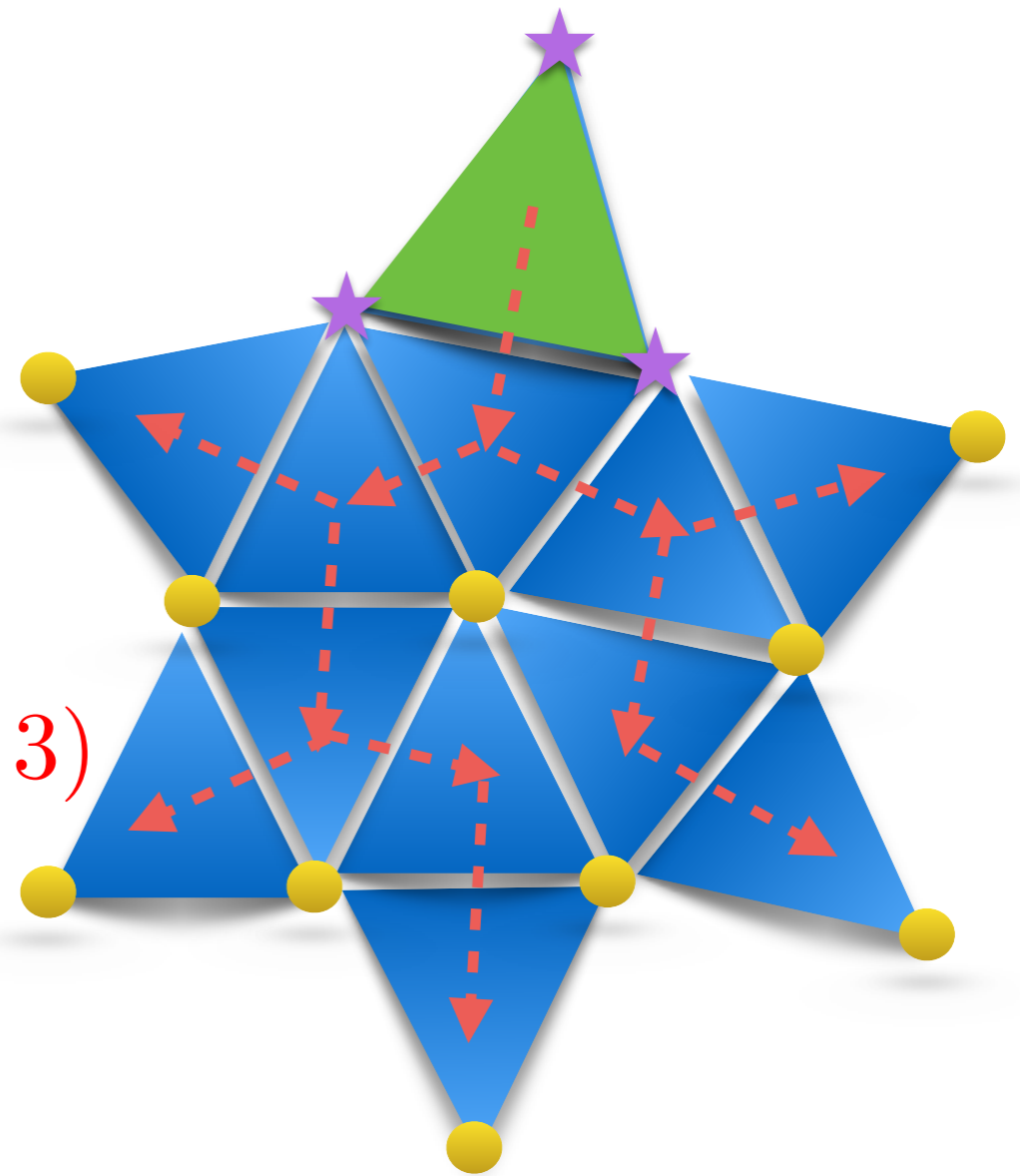
- ▶ Input:  $x(t) \ lcc(0)$

- ▶ Output:  $root(t) \ (3) \Delta lcc(t) \ (N - 3)$

- Decoding

- ▶ Input:  $lcc(0) \Delta lcc(t) \ root(t)$

- ▶ Output:  $\hat{x}(t)$



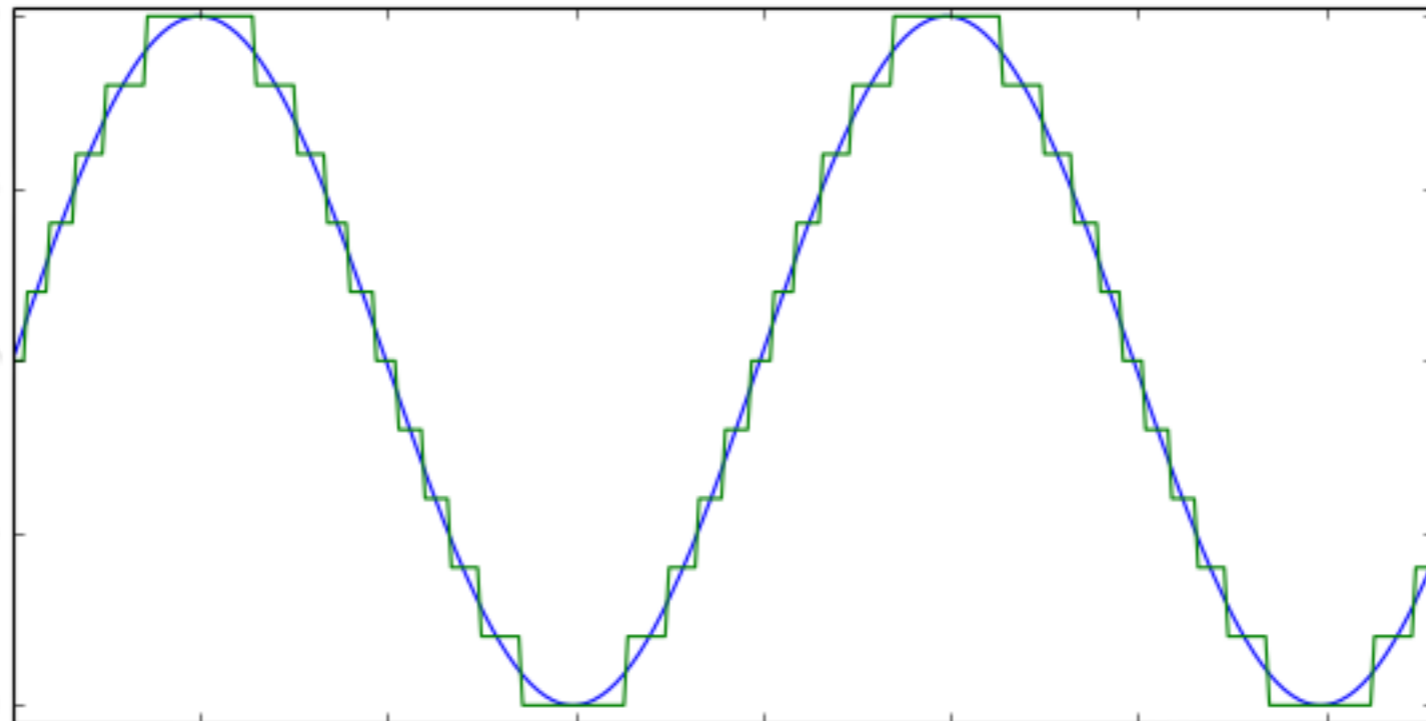
# Encoding & Decoding

- Spanning tree construction
  - No strong restriction
  - For irregular mesh, geometric info may be very helpful
- Traversal order, BFS or DFS?
  - Difference on compression ratio (< 5%)

# Quantization

- Mapping large set of values to smaller one
- Uniform quantization for  $x \in [-\sigma, \sigma]$

$$q(x) = \text{floor}(2^b x / \sigma)$$

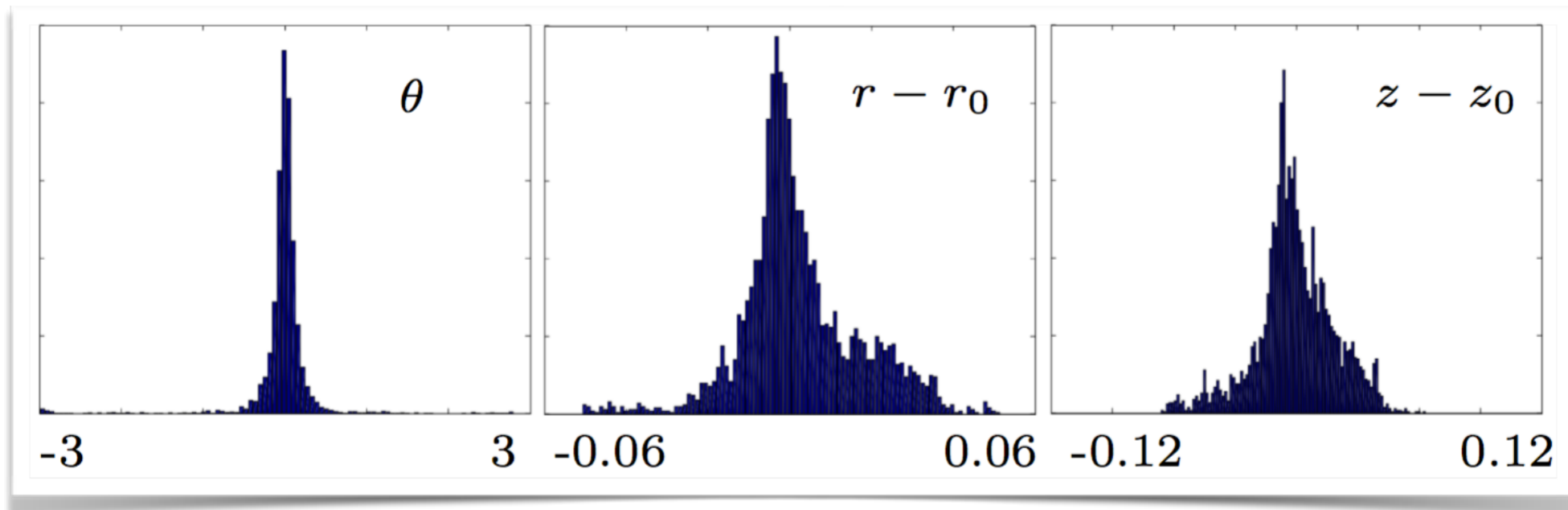


# Quantization

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- Optimal bits difference

$$b_{rh} = b_{\theta} - \lfloor 0.5 - \log_2(\sigma) \rfloor$$

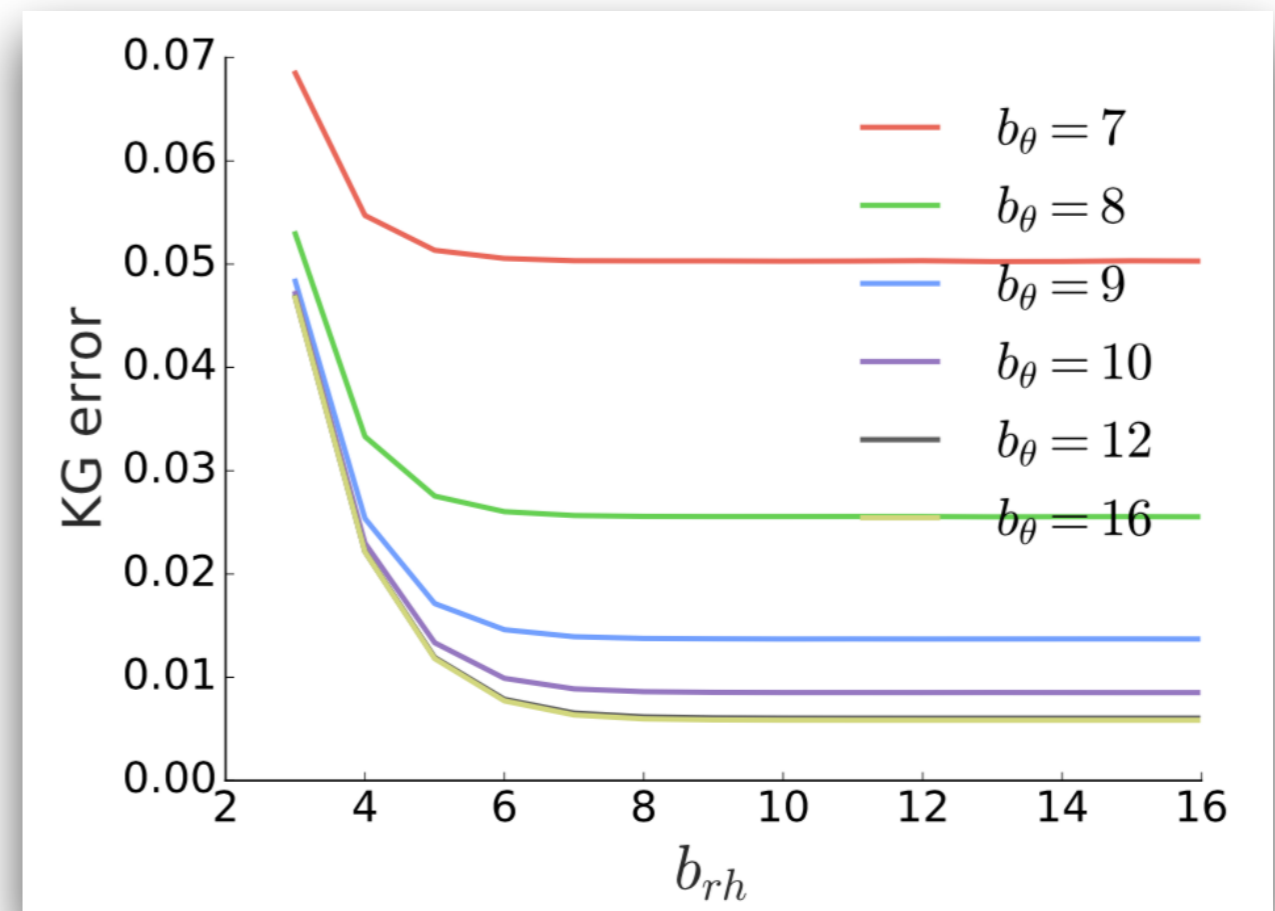




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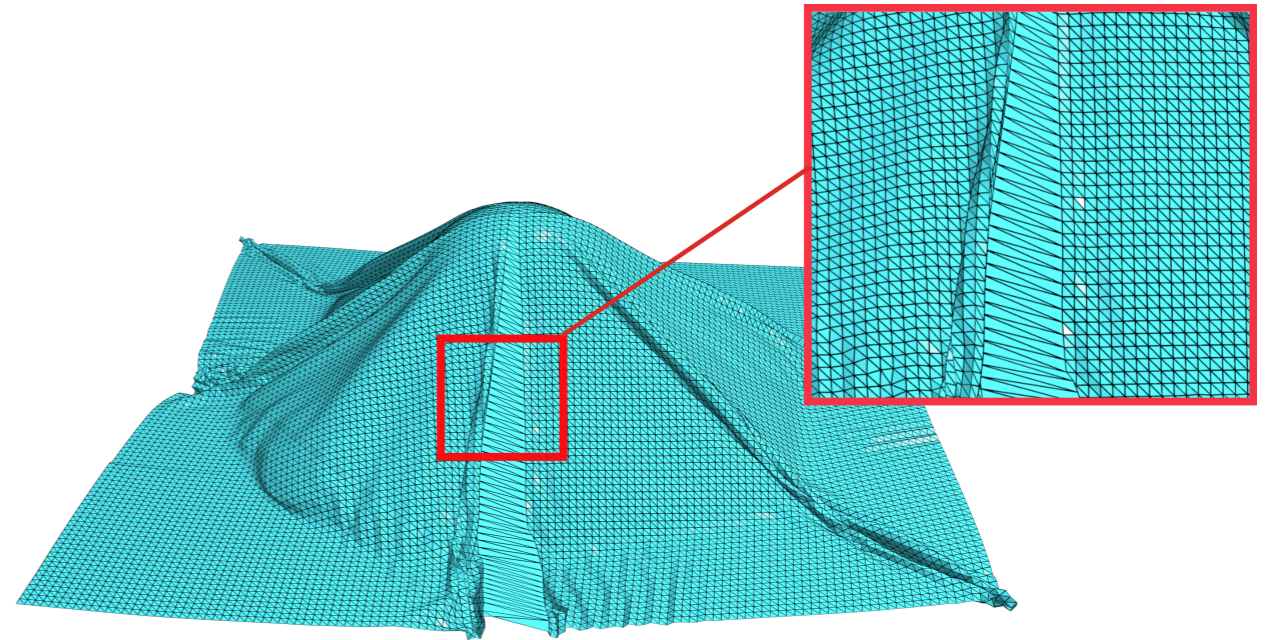


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- Optimal bits difference

$$b_{rh} = b_{\theta} - \lfloor 0.5 - \log_2(\sigma) \rfloor$$

- Naive implementation

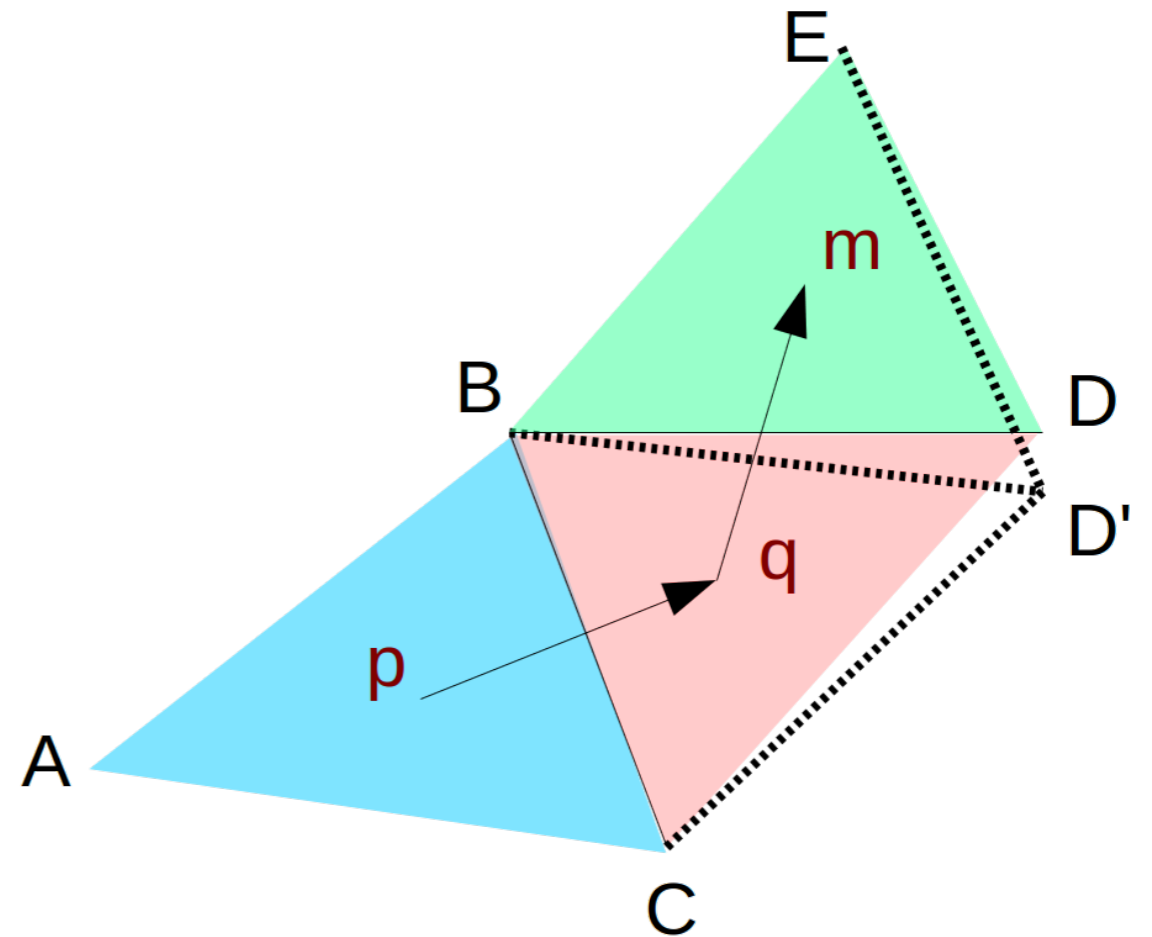


# Quantization

- Optimal bits difference

$$b_{rh} = b_{\theta} - \lfloor 0.5 - \log_2(\sigma) \rfloor$$

- Naive implementation
- Compensate the accumulation error



# Temporal Prediction



**Already encoded**

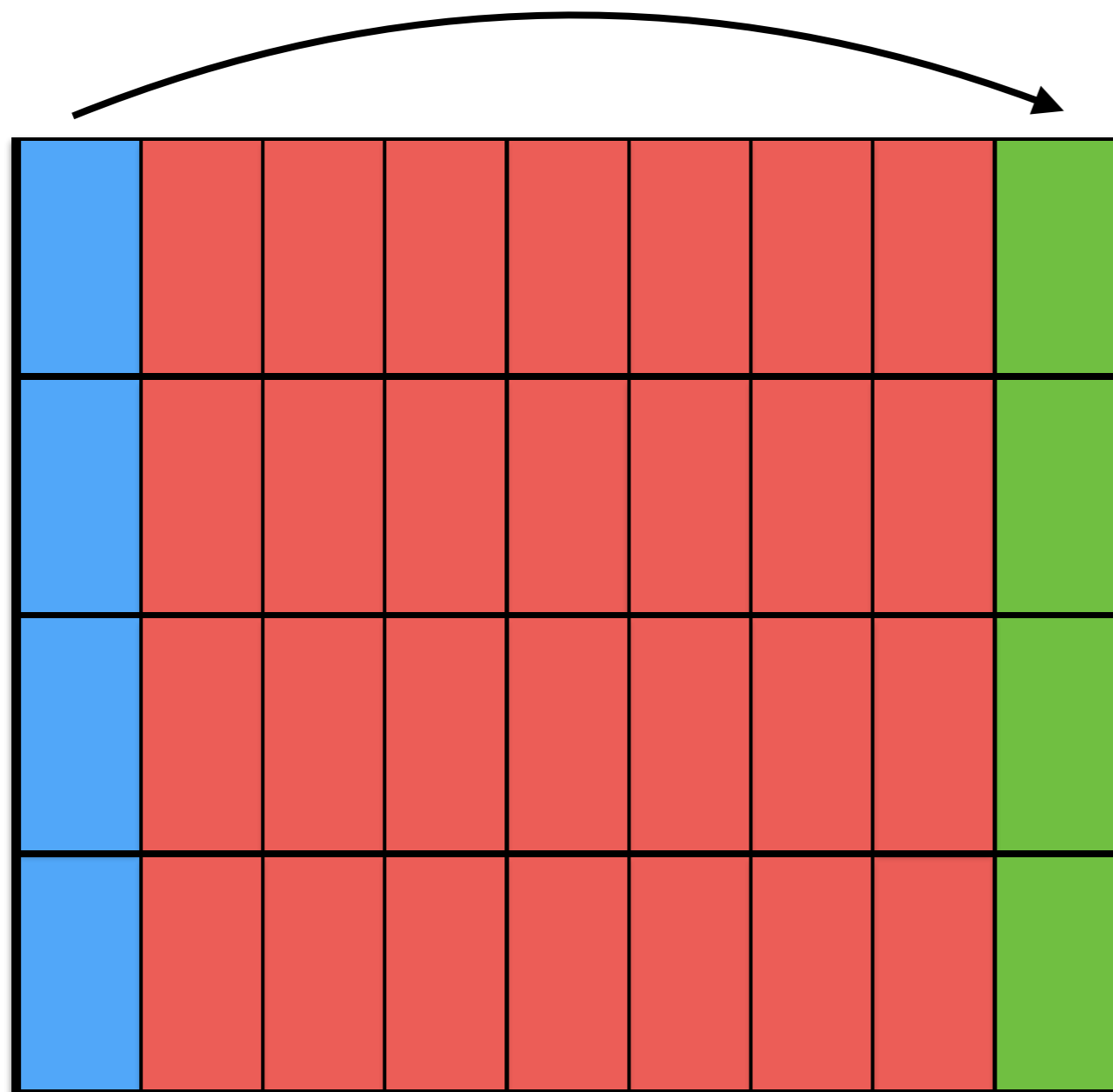


**Not encoded**



**Being encoded**

# Temporal Prediction



**Already encoded**

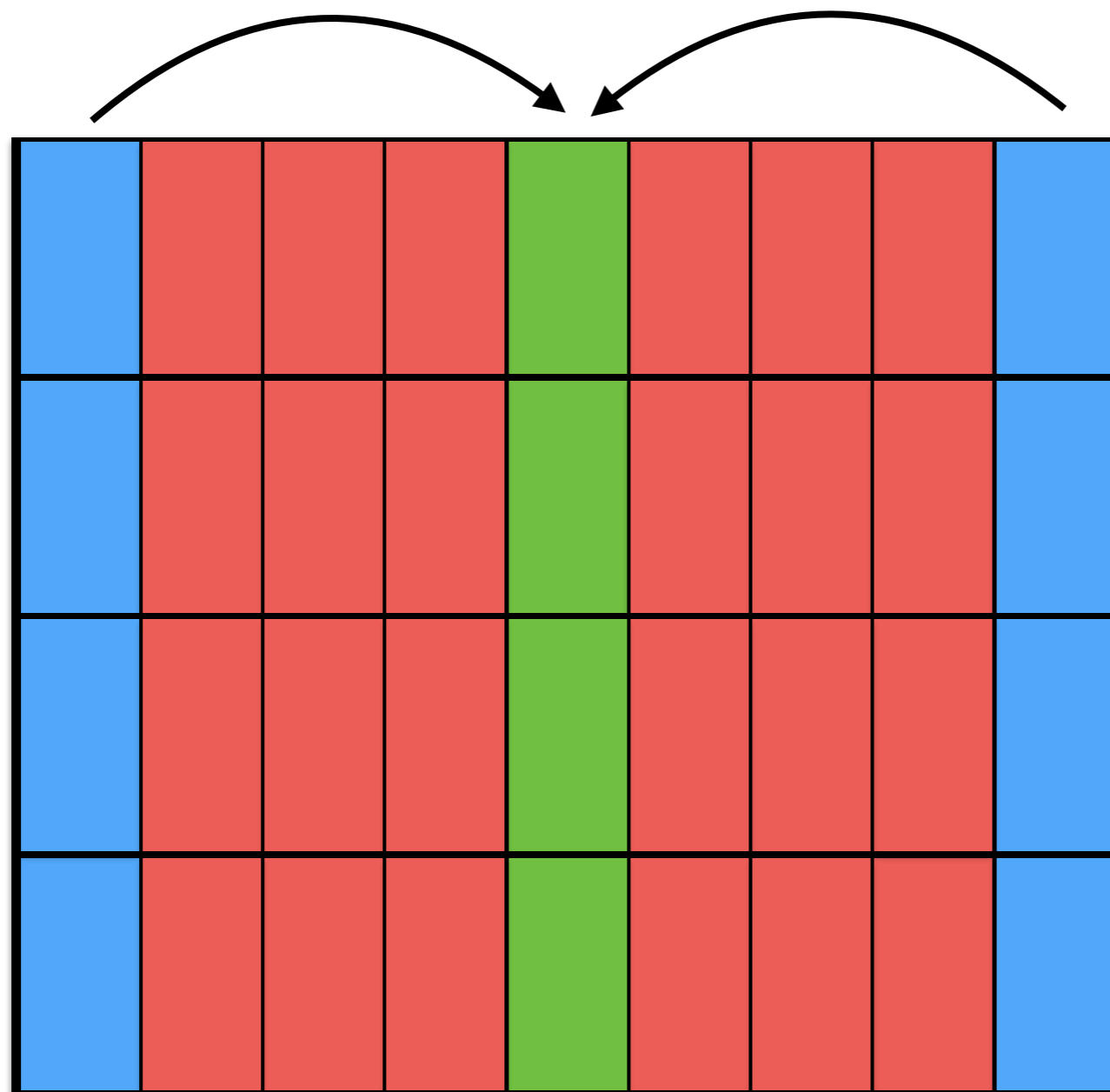


**Not encoded**



**Being encoded**

# Temporal Prediction



**Already encoded**

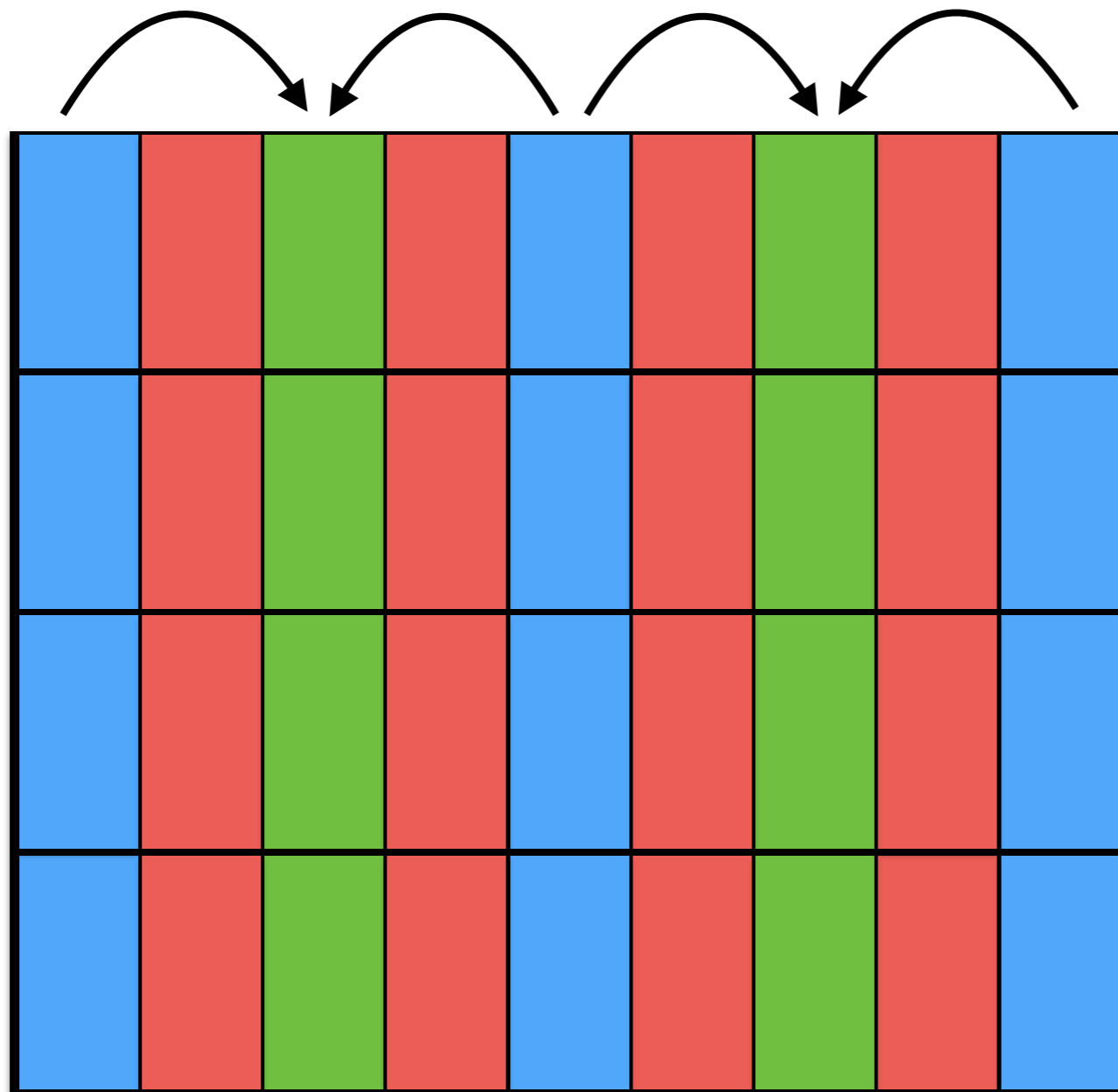


**Not encoded**



**Being encoded**

# Temporal Prediction



**Already encoded**

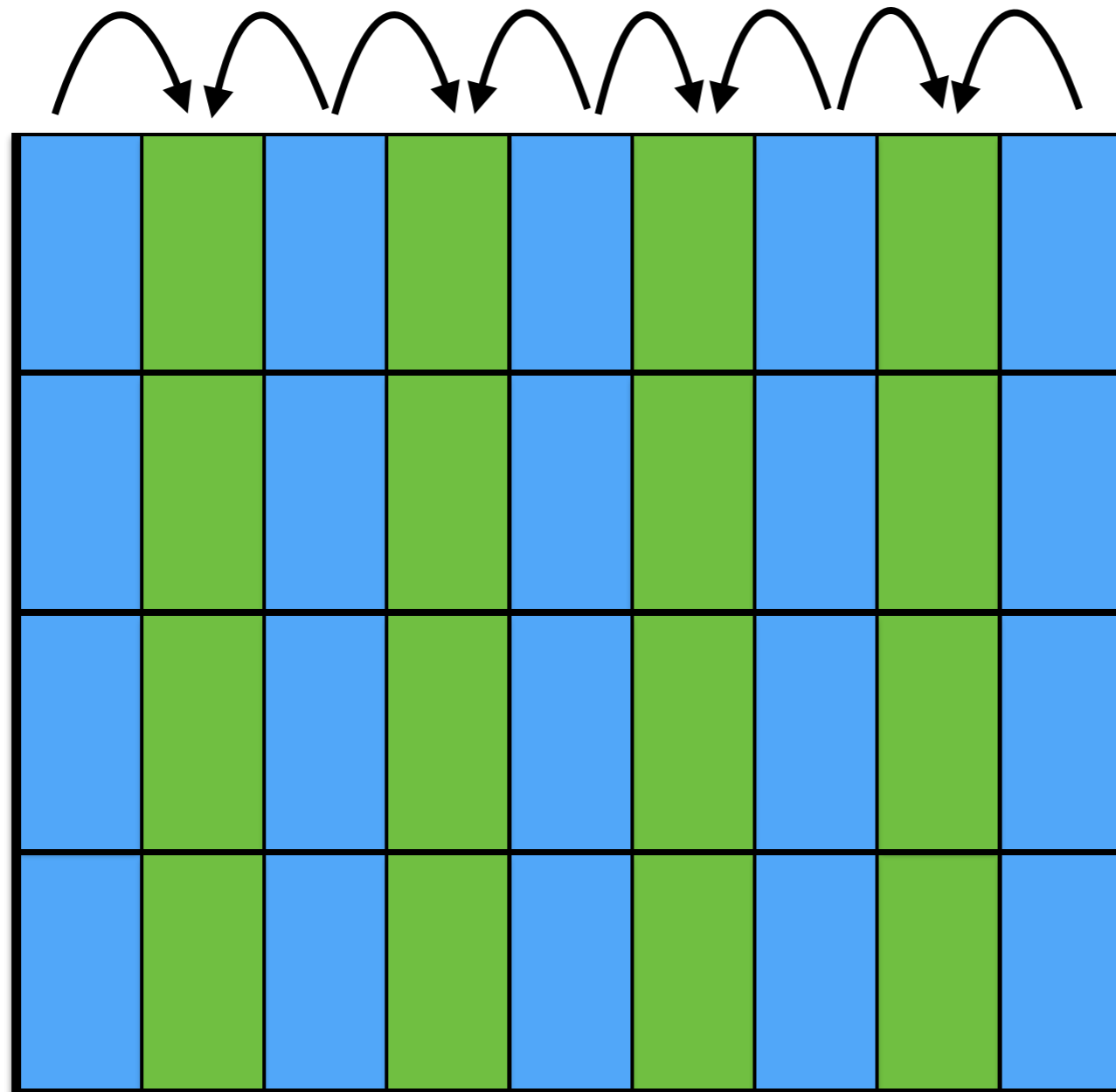


**Not encoded**



**Being encoded**

# Temporal Prediction



**Already encoded**



**Not encoded**



**Being encoded**



# Results

- Quality metric: KG error [Karni et al. 04]

$$e_{KG} = 100 \frac{\|\mathbf{F} - \hat{\mathbf{F}}\|}{\|\mathbf{F} - \mathbf{E}(\mathbf{F})\|}$$

- Error on visual appearance



# Results

- Bpvf: bits per vertex frame
  - 96 (3 components x 4 bytes x 8 bits) for uncompressed animation

# Results

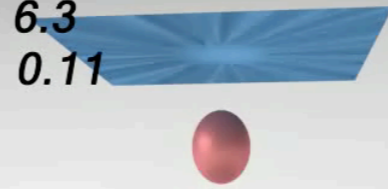
**Compressed**  
bpvf: 7.1  
KG: 0.09



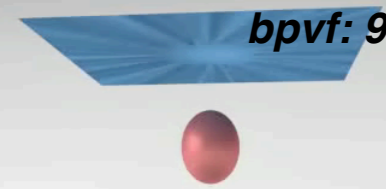
**Groundtruth**  
bpvf: 96



**Compressed**  
bpvf: 6.3  
KG: 0.11



**Groundtruth**  
bpvf: 96



*windy flag*

*falling cloth*

**Compressed**  
bpvf: 5.5  
KG: 0.1

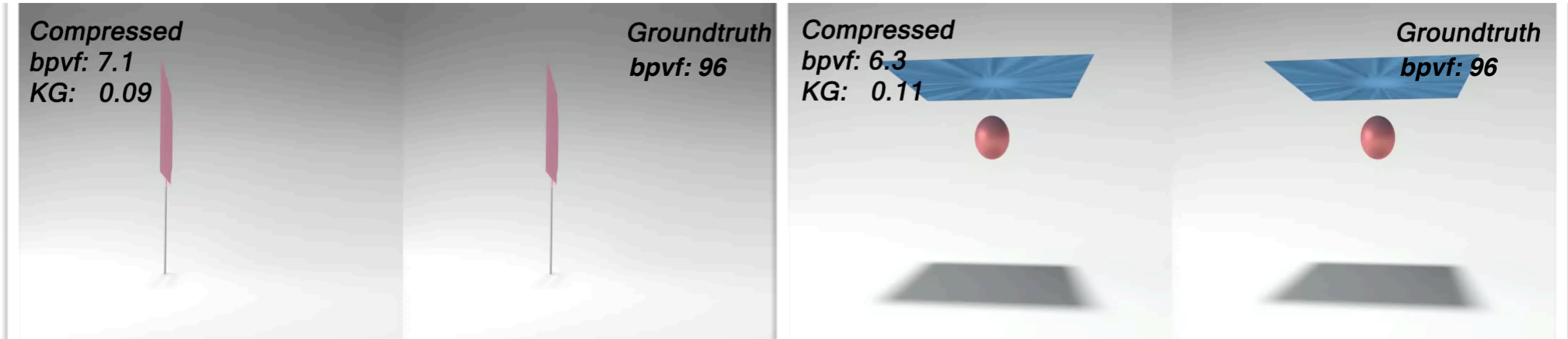


**Groundtruth**  
bpvf: 96



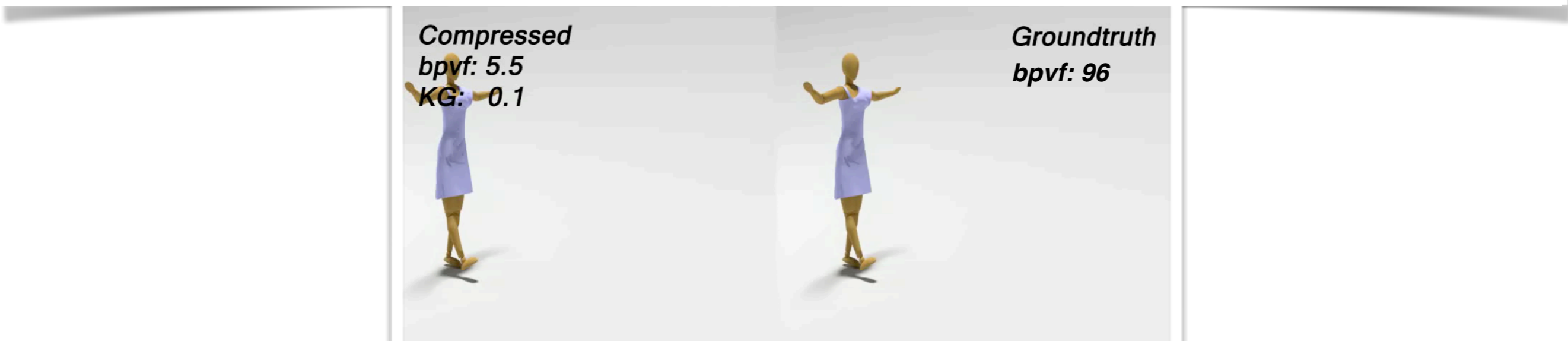
*dress*

# Results



*windy flag*

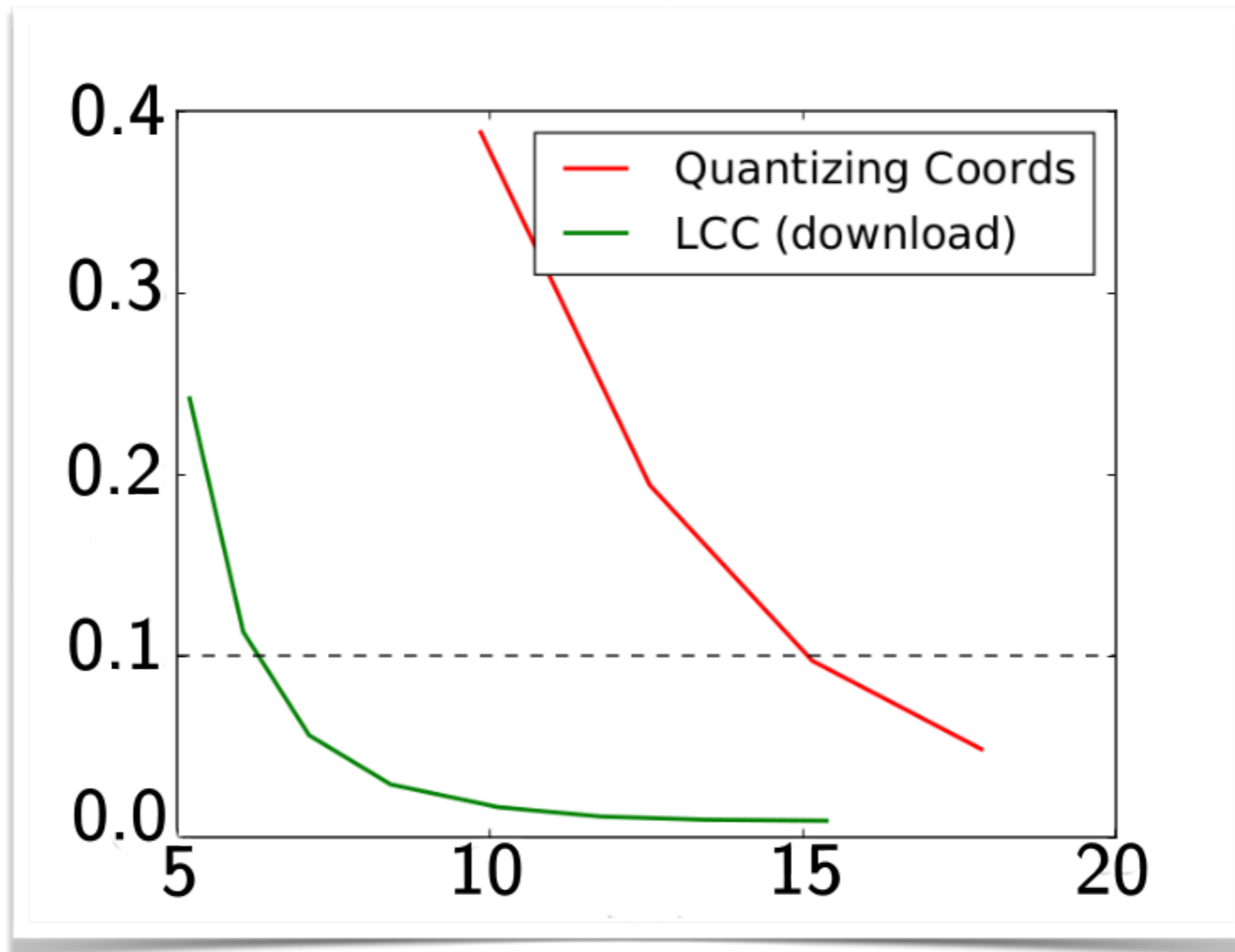
*falling cloth*



*dress*

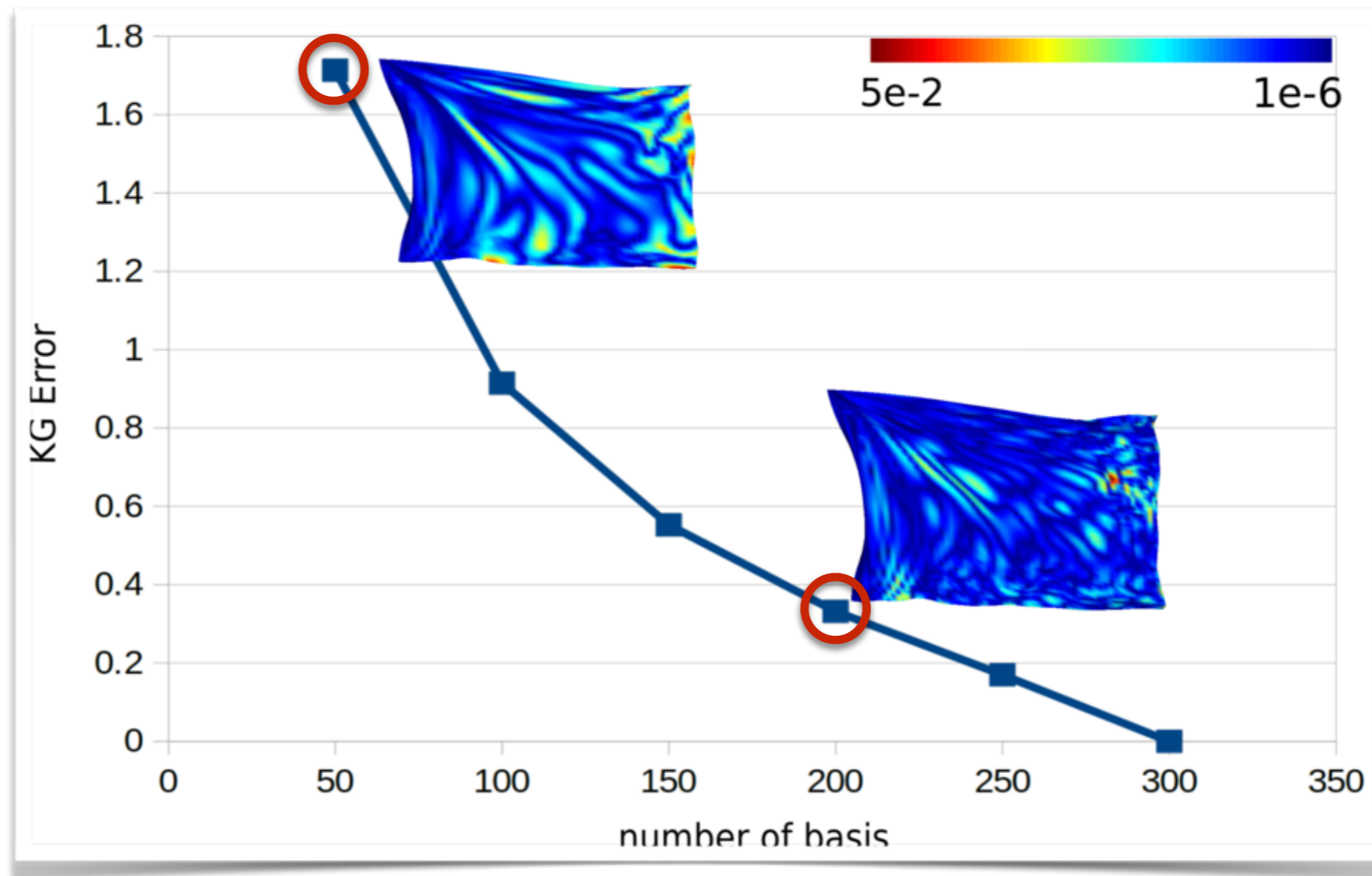
# Results

- With directly quantizing Euclidean coordinates



# Comparisons

- For spectral method [Alexa et al. 00]



# Results

- With SPC  
[Stefanoski et al.10]

# Results

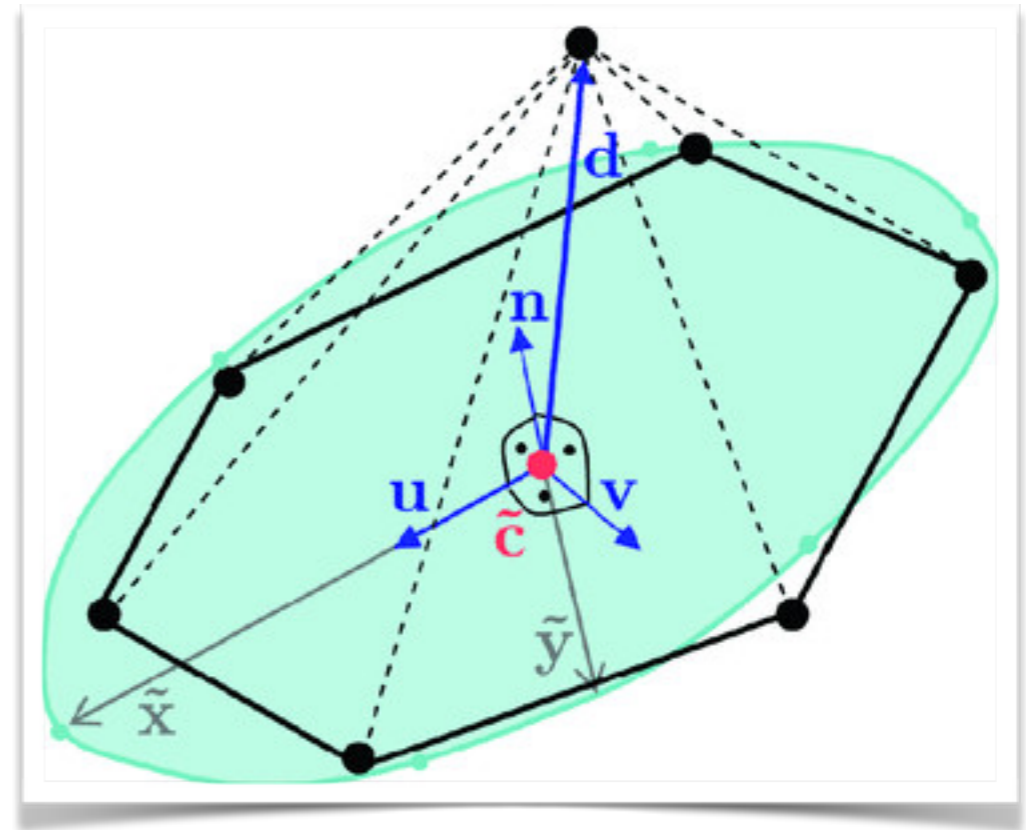
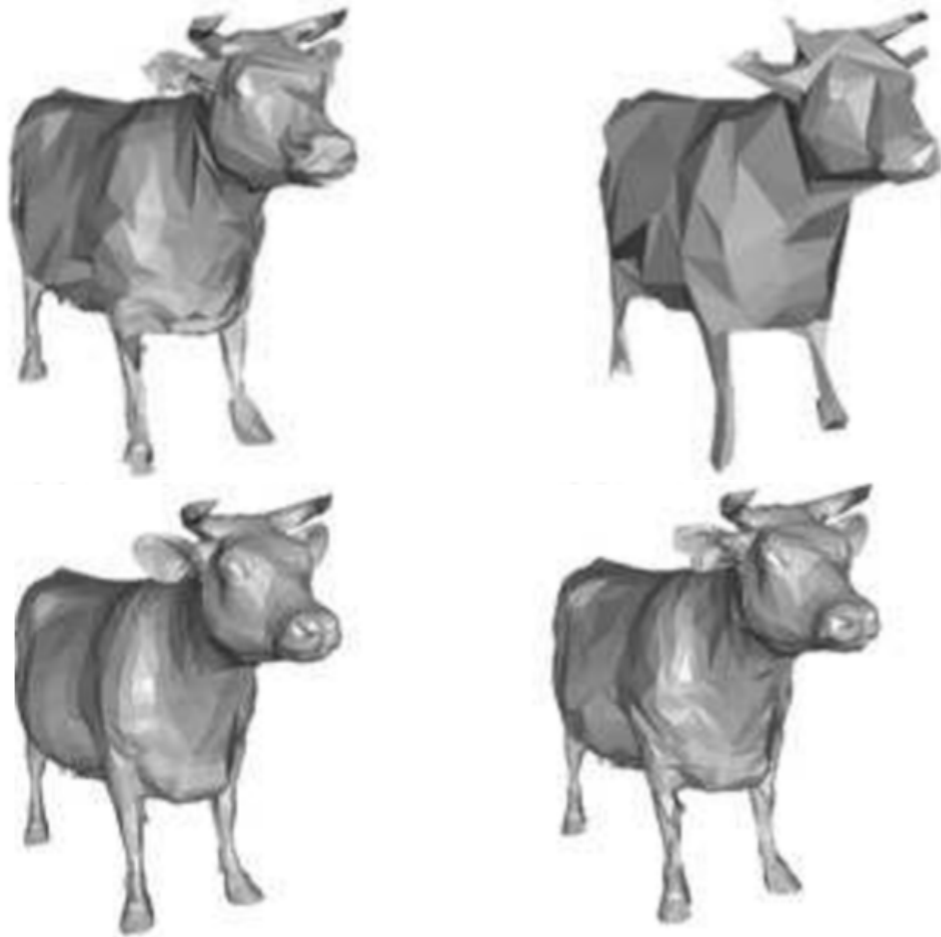
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# Results

- With SPC  
[Stefanoski et al.10]



# Results

temporal resolution = **9**



temporal resolution = **10**

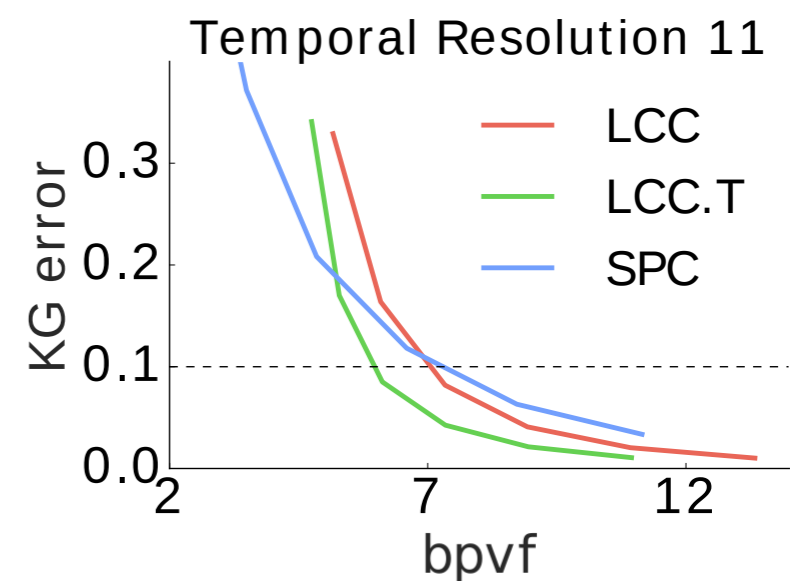
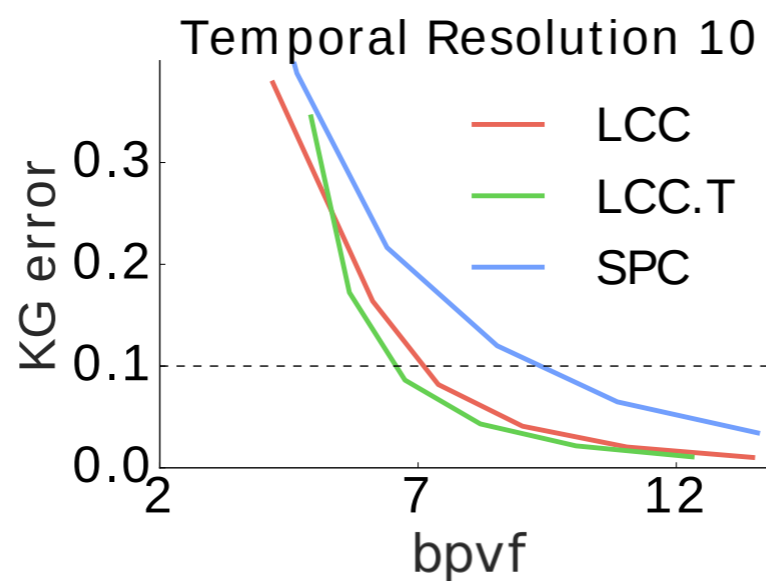
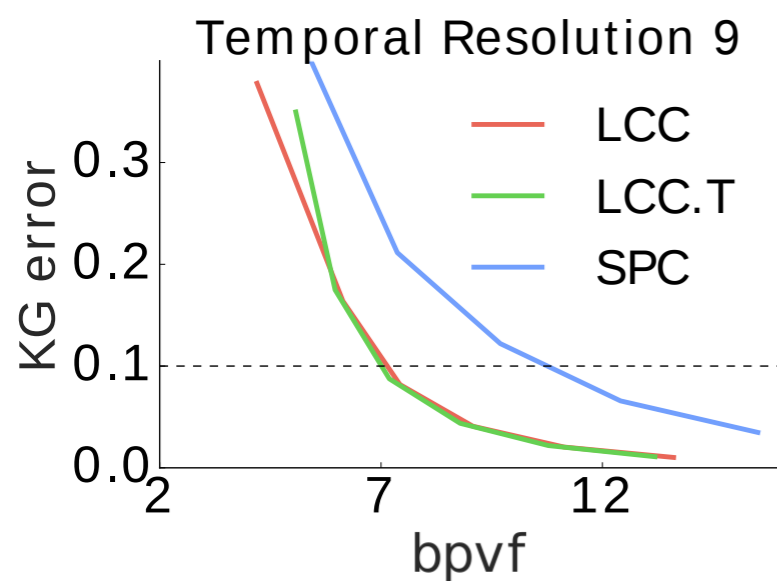
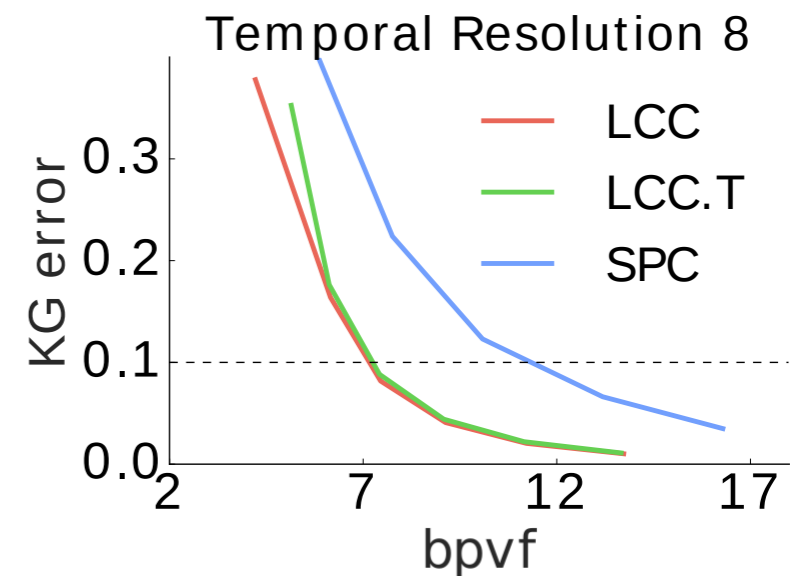
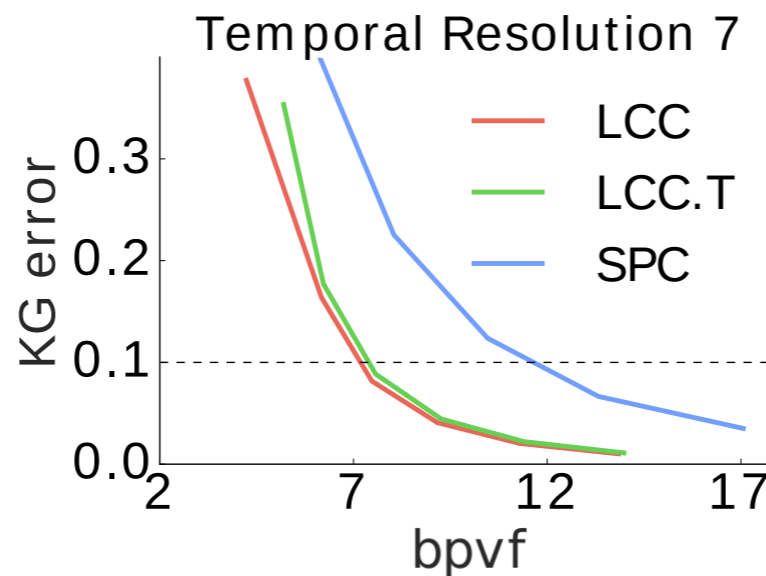


temporal resolution = **11**



# Results

- With SPC  
[Stefanoski et al.10]



temporal resolution = 9



temporal resolution = 10



temporal resolution = 11



# Timings

<b>animation</b>	<b>windy flag</b>	<b>falling cloth</b>	<b>dress</b>
<b>#vert</b>	4225	16641	104482
<b>#frms</b>	300	250	300
<b>comp. time (s)</b>	1.13	3.61	32.0
<b>decomp. time (s)</b>	1.0	2.6	27.0
<b>comp. #vert/ms</b>	1118	1154	980
<b>decomp. #vert/ms</b>	1268	1600	1161

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- Determine optimal bits with prescribed KG error



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- Compression of adaptively remeshed simulation
- Determine optimal bits with prescribed KG error
- More powerful temporal prediction

Thank you!